

Large fluctuations of the macroscopic current in diffusive systems: A numerical test of the additivity principle

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(Received 22 January 2010; published 8 April 2010)

Most systems, when pushed out of equilibrium, respond by building up currents of locally conserved observables. Understanding how microscopic dynamics determines the averages and fluctuations of these currents is one of the main open problems in nonequilibrium statistical physics. The additivity principle is a theoretical proposal that allows to compute the current distribution in many one-dimensional nonequilibrium systems. Using simulations, we validate this conjecture in a simple and general model of energy transport, both in the presence of a temperature gradient and in canonical equilibrium. In particular, we show that the current distribution displays a Gaussian regime for small current fluctuations, as prescribed by the central limit theorem, and non-Gaussian (exponential) tails for large current deviations, obeying in all cases the Gallavotti-Cohen fluctuation theorem. In order to facilitate a given current fluctuation, the system adopts a well-defined temperature profile different from that of the steady state and in accordance with the additivity hypothesis predictions. System statistics during a large current fluctuation is independent of the sign of the current, which implies that the optimal profile (as well as higher-order profiles and spatial correlations) are invariant upon current inversion. We also demonstrate that finite-time joint fluctuations of the current and the profile are well described by the additivity functional. These results suggest the additivity hypothesis as a general and powerful tool to compute current distributions in many nonequilibrium systems.

DOI: [10.1103/PhysRevE.81.041102](https://doi.org/10.1103/PhysRevE.81.041102)

PACS number(s): 05.40.-a, 02.50.-r, 05.70.Ln, 44.10.+i

I. INTRODUCTION

Understanding the physics of systems out of equilibrium remains challenging to a large extent, even in the simplest setting for which one could expect to make significant advances, which is that of a nonequilibrium steady state (NESS). Even in this simple situation difficulties abound mainly because out of equilibrium the dynamics plays a dominant role [1,2]. For instance, the phase space available to a system in a NESS depends crucially on the dynamics resulting in a probability measure for microscopic configurations which is not known in general for a NESS, as it will inherit this dependence on the dynamics [3]. This is in contrast to the equilibrium case, where the available phase space is uniquely determined by the Hamiltonian and the Gibbs distribution provides the probability measure for microscopic configurations. One can ask however questions on the statistics of the macroscopic observables characterizing a NESS, as for instance the current flowing through the system [4–7]. In equilibrium, the fluctuations of macroscopic quantities, which are a reflection of the hectic microscopic world, are strikingly independent of microscopic details, being solely determined by thermodynamic quantities as the entropy, free energy, etc. A natural way to seek a macroscopic theory of nonequilibrium phenomena is thus to investigate the fluctuations of macroscopic currents. Unveiling the relation between microscopic dynamics and current fluctuations has proven to be a difficult task [4–13], and up to now only few exactly solvable cases are understood. An important step in this direction has been the development of the Gallavotti-Cohen fluctuation theorem [12,13], which relates the probability of forward and backward currents reflecting the time-reversal symmetry of microscopic dynamics. However, we

still lack a general approach based on few simple principles. Recently, Bertini, De Sole, Gabrielli, Jona-Lasinio, and Landim [4] have introduced a hydrodynamic fluctuation theory (HFT) to study large dynamic fluctuations of diffusive systems. This is a very general approach which leads to a hard variational problem whose solution remains challenging in most cases. Simultaneously, Bodineau and Derrida [5–7] have conjectured an additivity principle for current fluctuations in one dimension which can be readily applied to obtain quantitative predictions and, together with HFT, seems to open the door to a general theory for nonequilibrium systems.

In this paper, we test in depth the validity of the additivity principle in a simple and very general diffusive model. In particular, we investigate the fluctuations of the energy current in the one-dimensional (1D) Kipnis-Marchioro-Pressuti (KMP) model of heat conduction, which represents at a coarse-grained level a large class of quasi-1D diffusive systems of technological and theoretical interest for which understanding current statistics is of central importance. Our results strongly support the validity of the additivity principle to describe current fluctuations in one dimension, both in the presence of a temperature gradient (NESS) and in canonical equilibrium. In particular, we find that the current distribution shows both Gaussian and non-Gaussian regimes, and obeys the Gallavotti-Cohen symmetry. The system modifies its temperature profile to facilitate a given current fluctuation, as predicted by the theory and this profile (as well as any other higher-order profile and spatial correlation) turns out to be independent of the sign of the current. We also explore physics beyond the additivity conjecture by studying the fluctuations of the total energy in the system, which exhibit the trace left by corrections to local equilibrium result-

ing from the presence of weak long-range correlations in the NESS. In addition, we extend the additivity hypothesis to study the joint fluctuations of the current and the profile.

The paper is structured as follows. In next section, we describe the additivity principle from a general perspective. Section III introduces the KMP model in one dimension. In Sec. IV we report the results of our simulations, together with a detailed comparison with theoretical predictions. Here we also show evidence of structure beyond the additivity scenario. Section V investigates the joint fluctuations of the current and the temperature profile, extending the additivity principle to understand these finite-time corrections. Finally, we present our conclusions in Sec. VI and a number of appendices describe some technical aspects of the discussion in the main text. Part of the work reported in this paper was presented in a shorter Letter [14].

II. ADDITIVITY PRINCIPLE

The additivity principle (to which we will also refer here as BD theory) is a conjecture first proposed by T. Bodineau and B. Derrida [5] that enables one to calculate the fluctuations of the current in 1D diffusive systems in contact with two boundary thermal baths at different temperatures, $T_L \neq T_R$. It is a very general conjecture of broad applicability, expected to hold for 1D systems of classical interacting particles, both deterministic or stochastic, independently of the details of the interactions between the particles or the coupling to the thermal reservoirs. The only requirement is that the system at hand must be diffusive, i.e., Fourier’s law must hold. If this is the case, the additivity principle predicts the full current distribution in terms of its first two cumulants. Equivalently, one may use the same formalism to study diffusive particle systems coupled to particle reservoirs at the boundaries at different chemical potentials and obeying Fick’s law, or any other open diffusive system characterized by a single locally conserved field. However, in this paper we stick for simplicity to the energy-diffusion version of the problem. Let $P_N(q, T_L, T_R, t)$ be the probability of observing a time-integrated current $Q_t = qt$ during a long-time t in a system of size N . This probability typically obeys a large deviation principle [15,16],

$$P_N(q, T_L, T_R, t) \sim e^{+t\mathcal{F}_N(q, T_L, T_R)}, \quad (1)$$

where $\mathcal{F}_N(q, T_L, T_R)$ is the current large deviation function (LDF), such that $\mathcal{F}_N(\langle q \rangle, T_L, T_R) = 0$ and $\mathcal{F}_N(q \neq \langle q \rangle, T_L, T_R) < 0$, with $\langle q \rangle = \lim_{t \rightarrow \infty} Q_t/t$. This means in particular that current fluctuations away from the average are exponentially unlikely in time. The additivity principle relates this probability with the product of probabilities for sustaining the same current in subsystems of lengths $N-n$ and n ,

$$P_N(q, T_L, T_R, t) = \max_T [P_{N-n}(q, T_L, T, t) P_n(q, T, T_R, t)]. \quad (2)$$

The maximization over the contact temperature T can be rationalized by writing the above probability as an integral over T of the product of probabilities for subsystems and noticing that these should obey also a large deviation principle akin to Eq. (1). Hence a saddle-point calculation in the

long- t limit leads to Eq. (2). In this way, Eq. (2) is only valid in the appropriate asymptotic limit. The additivity principle can be then rewritten for the large deviation function as

$$\mathcal{F}_N(q, T_L, T_R) = \max_T [\mathcal{F}_{N-n}(q, T_L, T) + \mathcal{F}_n(q, T, T_R)]. \quad (3)$$

We now may adopt a scaling form $\mathcal{F}_N(q, T_L, T_R) = N^{-1}\mathcal{G}(Nq, T_L, T_R)$ for the current LDF [5–7] and proceed by slicing iteratively the 1D system of length N into smaller and smaller segments. For small enough segments the temperature difference across each of them will be small, so for small currents $q \sim \mathcal{O}(N^{-1})$ each interval can be considered to be close to equilibrium and hence exhibits locally Gaussian fluctuations around the average current (given by Fourier’s law) at the leading order. In this way we obtain in the continuum limit the following variational form for \mathcal{G} [5–7]

$$\mathcal{G}(q) = - \min_{T_q(x)} \left\{ \int_0^1 \frac{[q + \kappa[T_q(x)]T'_q(x)]^2}{2\sigma[T_q(x)]} dx \right\}, \quad (4)$$

where we dropped the dependence on the baths for convenience. Here $\kappa(T)$ is the thermal conductivity characterizing Fourier’s law, $\langle Q_t \rangle/t = -\kappa(T)\nabla T$ and $\sigma(T)$ measures current fluctuations in equilibrium ($T_L = T_R$) and $\langle Q_t^2 \rangle/t = \sigma(T)/N$. The optimal temperature profile $T_q(x)$ derived from Eq. (4) by functional differentiation obeys

$$\kappa^2[T_q(x)] \left(\frac{dT_q(x)}{dx} \right)^2 = q^2 \{1 + 2\sigma[T_q(x)]K(q^2)\}, \quad (5)$$

where $K(q^2)$ is a constant which guarantees the correct boundary conditions, $T_q(0) = T_L$ and $T_q(1) = T_R$. In what follows we assume $T_L > T_R$ without loss of generality. Equations (4) and (5) completely determine the current distribution, which is in general non-Gaussian (except for very small current fluctuations) and obeys the Gallavotti-Cohen symmetry,

$$\mathcal{G}(-q) = \mathcal{G}(q) - \mathcal{E}q, \quad (6)$$

with \mathcal{E} a constant defined by [5]

$$\mathcal{E} = 2 \int_{T_L}^{T_R} \frac{\kappa(T)}{\sigma(T)} dT.$$

Moreover, the optimal profile solution of Eq. (5) is independent of the sign of the current, $T_q(x) = T_{-q}(x)$, a rather counterintuitive result which, together with the Gallavotti-Cohen relation, reflects the time-reversal symmetry of microscopic dynamics [12,13].

In the simplest case, when $K(q^2)$ is large enough for the right-hand side of Eq. (5) not to vanish—something that happens for currents close to the average, the optimal profile $T_q(x)$ is monotone and we have ($T_L > T_R$)

$$\frac{dT_q(x)}{dx} = - \frac{|q|}{\kappa[T_q(x)]} \sqrt{1 + 2\sigma[T_q(x)]K(q^2)}, \quad (7)$$

Using this expression in Eq. (4) leads to

$$\mathcal{G}(q) = \int_{T_R}^{T_L} \frac{\kappa(T)}{\sigma(T)} \left\{ q - |q| \frac{1 + K(q^2)\sigma(T)}{\sqrt{1 + 2K(q^2)\sigma(T)}} \right\} dT, \quad (8)$$

and integrating Eq. (7) above over the whole interval $x \in [0, 1]$ we obtain an implicit equation for $K(q^2)$,

$$|q| = \int_{T_R}^{T_L} \frac{\kappa(T)}{\sqrt{1 + 2K(q^2)\sigma(T)}} dT. \quad (9)$$

In many applications it is interesting to work with the Legendre transform of the large deviation function,

$$\mu(\lambda) \equiv \frac{1}{N} \max_q [\mathcal{G}(q) + \lambda q], \quad (10)$$

or equivalently $\mu(\lambda) = N^{-1} [\mathcal{G}(q_o) + \lambda q_o]$, with $q_o(\lambda)$ given by $\partial_q \mathcal{G}(q_o) + \lambda = 0$. By noticing that $\partial_q \mathcal{G}(q) = \mathcal{G}'/q + Kq$, it then follows for monotone profiles

$$\mu(\lambda) = -\frac{K(\lambda)}{N} \left\{ \int_{T_R}^{T_L} \frac{\kappa(T)}{\sqrt{1 + 2K(\lambda)\sigma(T)}} dT \right\}^2, \quad (11)$$

where $K(\lambda)$ is now obtained from

$$\lambda = \int_{T_R}^{T_L} \left[\frac{\text{sgn}[q_o(\lambda)]}{\sqrt{1 + 2K(\lambda)\sigma(T)}} - 1 \right] dT, \quad (12)$$

and $\text{sgn}(q) = |q|/q$ is the sign function. The function $\mu(\lambda)$ can be viewed as the conjugate *potential* to $\mathcal{G}(q)$, with λ the parameter conjugate to the current q , a relation equivalent to the free energy being the Legendre transform of the internal energy in thermodynamics, with the temperature as conjugate parameter to the entropy.

When the constant K is negative enough for the right-hand side of Eq. (5) to vanish at some point, the resulting optimal profile $T_q(x)$ becomes nonmonotone. In this case it can be shown [5] that the expressions for $\mathcal{G}(q)$ and $K(q^2)$, or their equivalent formulas in λ space, are just the analytic continuation of their monotone-case counterparts. Appendix A shows the particular expressions for the current LDF and the associated optimal profile, both in the monotone and non-monotonous cases, as derived when applying this general scheme to the particular model of interest in this paper, the KMP model of heat conduction [17].

Before continuing with the description of this model, it is worth noticing that the additivity principle can be better understood within the context of hydrodynamic fluctuation theory of Bertini *et al.* [4], which provides a variational principle for the most probable (possibly time-dependent) profile responsible of a given current fluctuation. The probability of observing a particular history of the temperature profile $T(x, t)$ and the rescaled current $j(x, t)$ during a macroscopic time is, according to HFT [4, 18],

$$P(\{T(x, t), j(x, t)\}) \sim \exp(-N\mathcal{I}_t[T, j]), \quad (13)$$

where the functional \mathcal{I}_t can be written as

$$\mathcal{I}_t[T, j] = \int_0^t d\tau \int_0^1 dx \frac{[j(x, \tau) + \kappa[T(x, \tau)]T'(x, \tau)]^2}{2\sigma[T(x, \tau)]}, \quad (14)$$

and where the rescaled current field is related to the temperature profile via the continuity equation $\partial_\tau T(x, \tau) + \partial_x j(x, \tau) = 0$. The large deviation function of the integrated current is then

$$P\left(\frac{Q_t}{t} = \frac{q}{N}\right) \sim \exp\left[+\frac{t}{N}\mathcal{G}(q)\right], \quad (15)$$

where $\mathcal{G}(q)$ is related to $\mathcal{I}_t[T, j]$ via

$$\mathcal{G}(q) = \lim_{t \rightarrow \infty} \left(-\frac{1}{t} \min_{T(x, \tau)} \mathcal{I}_t[T, j] \right)_{j(x, \tau)}, \quad (16)$$

with the constraint

$$q = \frac{1}{t} \int_0^t j(x, \tau) d\tau, \quad (17)$$

and $T(x, \tau)$ and $j(x, \tau)$ coupled via the above continuity equation. Solving this time-dependent problem to obtain explicit predictions for the current LDF remains a challenge in most cases. The additivity principle, which on the other hand can be readily applied to obtain quantitative predictions, is equivalent within HFT to the hypothesis that the optimal profiles $T(x, \tau)$ and $j(x, \tau)$ solution of the variational problem (16) and (17) are time independent, in which case we recover Eq. (4) for $\mathcal{G}(q)$. In some special cases this approximation breaks down for extreme current fluctuations [4, 18, 19], but even so the additivity hypothesis correctly predicts the current LDF in a very large current interval, making it very appealing.

III. KMP MODEL

The system is defined on a 1D open lattice with N sites [17]. Each site models an harmonic oscillator which is mechanically uncoupled from its nearest neighbors but interact with them through a random process which redistributes energy locally. In this way, a configuration is given by $C \equiv \{e_i, i=1 \dots N\}$, where $e_i \in \mathbb{R}_+$ is the energy of site i and the stochastic dynamics proceeds through random energy exchanges between randomly chosen nearest neighbors, i.e., $(e_i, e_{i+1}) \rightarrow (e'_i, e'_{i+1})$ for $i \in [1, N-1]$ such that

$$e'_i = p(e_i + e_{i+1}),$$

$$e'_{i+1} = (1-p)(e_i + e_{i+1}), \quad (18)$$

with $p \in [0, 1]$ a homogeneous random number so $e_i + e_{i+1} = e'_i + e'_{i+1}$. In addition, boundary sites ($i=1, N$) may also exchange energy with boundary heat baths at temperatures T_L for $i=1$ and T_R for $i=N$, i.e., $e_{1,N} \rightarrow e'_{1,N}$ such that

$$e'_{1,N} = p(\tilde{e}_{L,R} + e_{1,N}), \quad (19)$$

with $\tilde{e}_{L,R}$ randomly drawn at each step from a Gibbs distribution at the corresponding temperature, $\beta_k \exp(-\beta_k \tilde{e}_k)$, k

$=L,R$, and $p \in [0,1]$ random. For $T_L \neq T_R$ KMP proved [17] that the system reaches a nonequilibrium steady state which, in the $N \rightarrow \infty$ hydrodynamic scaling limit, is described by Fourier's law with a nonzero average current

$$\langle q \rangle = -\kappa(T) \frac{dT_{st}(x)}{dx}, \quad x \in [0,1], \quad (20)$$

with $\kappa(T) = \frac{1}{2}$ and a linear energy profile

$$T_{st}(x) = T_L + x(T_R - T_L). \quad (21)$$

In addition, convergence to the local Gibbs measure was proven in this limit [17], meaning that $e_i, i \in [1,N]$, has an exponential distribution with local temperature $T_{st}[x=i/(N+1)]$ in the thermodynamic limit. However, corrections to local equilibrium (LE), though vanishing in the $N \rightarrow \infty$ limit, become apparent at the fluctuation level [26,27], as we will show below. Moreover, the fluctuations of the current in equilibrium ($T_L = T_R$) are described by $\sigma(T) = T^2$. It is also worth noticing that KMP dynamics obeys the local detailed balance condition and is therefore time reversible [13], see Appendix D. In this way we expect the Gallavotti-Cohen symmetry to hold in this system, see Eq. (6).

The KMP model plays a fundamental role in nonequilibrium statistical physics as a benchmark to test theoretical advances and represents at a coarse-grained level a large class of quasi-1D diffusive systems of technological and theoretical interest. In this way, understanding how the energy current fluctuates in the KMP model is of central importance to understand current statistics in more realistic systems. Furthermore, the KMP model is an optimal candidate to test the additivity principle because: (i) one can solve Eqs. (4) and (5) to obtain explicit predictions for its current LDF and (ii) its simple dynamical rules allow a detailed numerical study of current fluctuations.

In Appendix A we apply the additivity formalisms of the previous section to study current fluctuations in the KMP model. In particular, we use Eqs. (4) and (5) to derive analytical expressions for the current LDF $\mathcal{G}(q)$ and the associated optimal profiles $T_q(x)$, see Figs. 1 and 2. In this case it can be shown that optimal profiles can be either monotone or nonmonotone with a single maximum, see Appendix A for the explicit calculations. In what follows, we compare this set of analytical predictions with computer simulation results.

IV. NUMERICAL TEST OF THE ADDITIVITY PRINCIPLE

The simplicity and versatility of the KMP model allows us to obtain explicit analytical expressions for $\mathcal{G}(q)$ and $T_q(x)$ based on the additivity conjecture, see Appendix A. Figs. 1 and 2 show the theoretical current LDF and the associated optimal profiles, respectively. We find that $P_N(q, T_L, T_R, t)$ is Gaussian around $\langle q \rangle$ with variance $\sigma(T)$, while non-Gaussian, exponential tails develop far from $\langle q \rangle$, with decay rates given by the inverse bath temperatures. Exploring by standard simulations these tails to check BD theory is very difficult, since LDFs involve by definition exponential unlikely rare events. This is corroborated in Appendix B, where

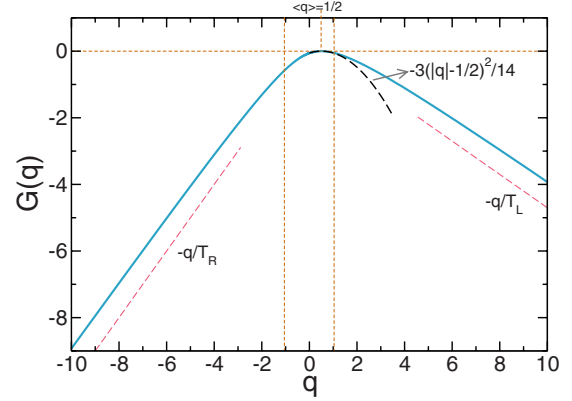


FIG. 1. (Color online) $\mathcal{G}(q)$ for the KMP model as derived from the additivity principle for $T_L=2$ and $T_R=1$. Notice the linear decay for large enough $|q|$. Vertical lines signal the crossover from monotone ($|q| < \pi/3$) to nonmonotone ($|q| > \pi/3$) optimal profiles. The Gaussian approximation for $q \approx \langle q \rangle$, $\mathcal{G}(q) \approx -3(|q| - \frac{1}{2})^2/14$, is also shown.

$\mathcal{G}(q)$ is measured directly but we are unable to gather enough statistics in the tails of the current distribution to validate or falsify the additivity hypothesis. Recently Giardinà, Kurchan, and Peliti [20] have introduced an efficient method to measure LDFs in many-particle systems based on a modification of the dynamics so that the rare events responsible of the large deviation are no longer rare [21]. This method yields the Legendre transform of the current LDF, $\mu(\lambda)$, see Eq. (10). If $U_{C'C}$ is the transition rate from configuration C to C' of the associated stochastic process, the modified dynamics is defined as $\tilde{U}_{C'C}(\lambda) = U_{C'C} \exp(\lambda J_{C'C})$, where $J_{C'C}$ is the elementary current involved in the transition $C \rightarrow C'$. It can be then shown (see Appendix C) that the natural logarithm of the largest eigenvalue of matrix $\tilde{U}(\lambda)$ gives $\mu(\lambda)$. The method of Ref. [20] thus provides a way to measure $\mu(\lambda)$ by evolving many copies or clones of the system using the modified dynamics $\tilde{U}(\lambda)$, see Appendix C.

We applied the method of Giardinà *et al.* to measure $\mu(\lambda)$ for the 1D KMP model with $N=50$, $T_L=2$, and $T_R=1$, see Fig. 3, top panel. The agreement with BD theory is excellent

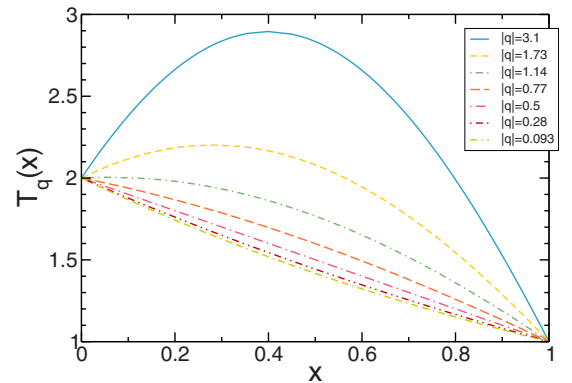


FIG. 2. (Color online) Optimal $T_q(x)$ for different values of $|q|$, both in the monotone and nonmonotone regimes, for $T_L=2$ and $T_R=1$. The optimal profiles are independent of the sign of the current, $T_q(x) = T_{-q}(x)$.

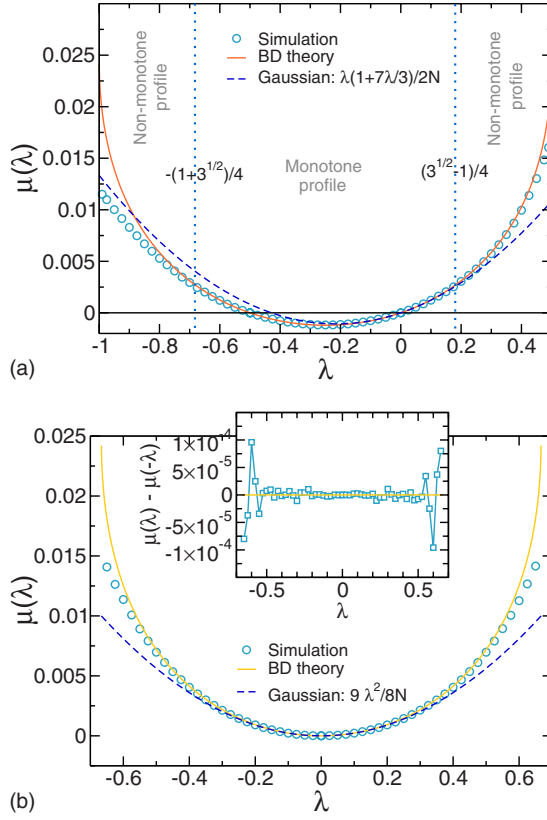


FIG. 3. (Color online) Legendre transform of the current LDF for the KMP model in one dimension in a temperature gradient (top, $T_L=2$ and $T_R=1$) and in equilibrium (bottom, $T_L=1.5=T_R$). Symbols correspond to numerical simulations, full lines to BD theory, and dashed lines to Gaussian approximations (see text). Error bars (with five standard deviations) are always smaller than symbol sizes. The vertical dotted lines in top panel signal the transition between deviations for which the associated temperature profile is monotone (inner region) or nonmonotone (outer region). In equilibrium profiles are nonmonotone for all current fluctuations. The inset in the bottom panel tests the Gallavotti-Cohen relation in equilibrium by plotting the difference $\mu(\lambda) - \mu(-\lambda)$.

for a wide λ interval, say $-0.8 < \lambda < 0.45$, which corresponds to a very large range of current fluctuations, see inset to Fig. 11 in Appendix C. Moreover, the deviations observed for extreme current fluctuations are due to known limitations of the algorithm [14,20–22], so no violations of additivity are observed. Notice that these spurious differences seem to occur earlier for currents *against the gradient*, i.e., $\lambda < 0$. In fact, we can use the Gallavotti-Cohen symmetry, which in λ space now reads $\mu(\lambda) = \mu(-\lambda - \mathcal{E})$ with $\mathcal{E} = (T_R^{-1} - T_L^{-1})$, to bound the range of validity of the algorithm: Violations of the fluctuation relation indicate a systematic bias in the estimations provided by the method of Ref. [20], see also [22]. Fig. 4. shows that the Gallavotti-Cohen symmetry holds in the large current interval for which the additivity principle predictions agree with measurements, thus confirming its validity in this range. However, we cannot discard the possibility of an additivity breakdown for extreme current fluctuations due to the onset of time-dependent optimal profiles expected in general in HFT [4], although we stress that such scenario is not observed here. Exploring this interesting pos-

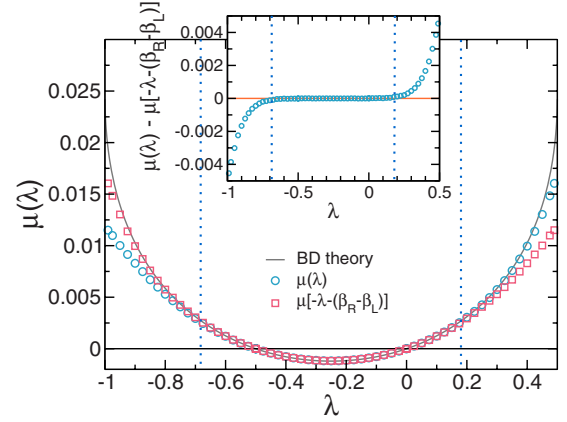


FIG. 4. (Color online) Measured $\mu(\lambda)$ and $\mu(-\lambda - \mathcal{E})$ superimposed. The Gallavotti-Cohen symmetry is satisfied for a wide range of λ . The inset shows the difference $\mu(\lambda) - \mu(-\lambda - \mathcal{E})$.

sibility would require a modification of the advanced Monte Carlo scheme of Ref. [20].

We also measured the current LDF in canonical equilibrium, i.e., for $T_L=T_R=1.5$, see the bottom panel in Fig. 3. The agreement with BD theory is again excellent within the range of validity of our measurements, which expands a wide current interval, see inset to Fig. 3, and the fluctuation relation is verified except for extreme currents deviations, where the algorithm fails to provide reliable results. Notice that, both in the presence of a temperature gradient and in canonical equilibrium, $\mu(\lambda)$ is parabolic around $\lambda=0$ meaning that current fluctuations are Gaussian for $q \approx \langle q \rangle$, as demanded by the central limit theorem, see Eqs. (A15) and (A16) in Appendix A. This observation is particularly interesting in equilibrium, where canonical and microcanonical ensembles behave differently (see below).

The additivity principle leads to the minimization of a functional of the temperature profile, $T_q(x)$, see Eqs. (4) and (5). A relevant question is whether this optimal profile is actually observable. We naturally define $T_q(x)$ as the average energy profile adopted by the system during a large deviation event of (long) duration t and time-integrated current qt , measured at an *intermediate time* $1 \ll \tau \ll t$, i.e., $T_q(x) \equiv T_q^{\text{mid}}(x)$. Fig. 5 shows the measured $T_q^{\text{mid}}(x)$ for both the equilibrium and nonequilibrium settings, and the agreement with BD predictions is again very good in all cases, with discrepancies appearing only for extreme current fluctuations, as otherwise expected. See also Fig. 14 in Appendix B. This confirms the idea that the system indeed modifies its temperature profile to facilitate the deviation of the current, validating the additivity principle as a powerful conjecture to compute both the current LDF and the associated optimal profiles. Our numerical results show also that optimal profiles are indeed independent of the sign of the current, $T_\lambda(x) = T_{-\lambda - \mathcal{E}}(x)$ or equivalently $T_q(x) = T_{-q}(x)$, a counterintuitive symmetry resulting from the reversibility of microscopic dynamics. Notice that in the equilibrium case ($T_L=T_R$) optimal temperature profiles are always nonmonotone with a single maximum for any current fluctuation $q \neq \langle q \rangle$ (the stationary profile is obviously flat). This is in stark contrast to the behavior predicted for current fluctuations in *microca-*

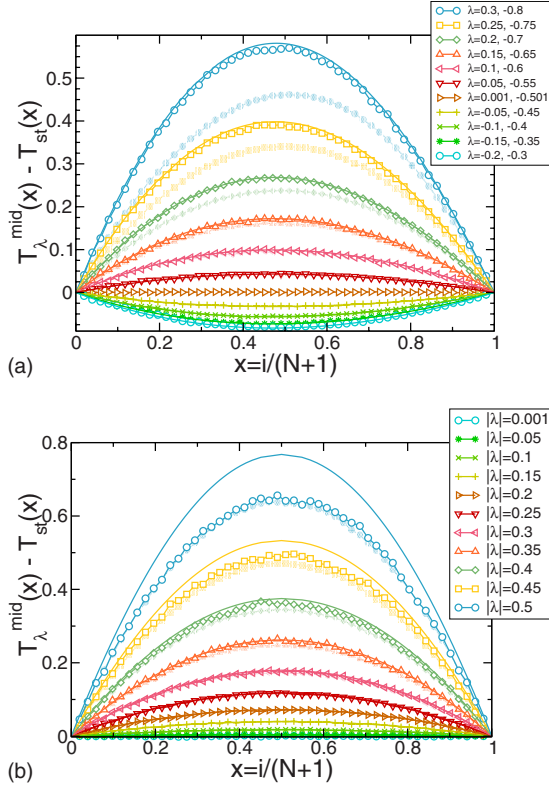


FIG. 5. (Color online) Excess temperature profiles for different current fluctuations, for a system subject to a temperature gradient (top, $T_L=2$, $T_R=1$) and in equilibrium (bottom, $T_L=1.5=T_R$). In all cases, agreement with BD theoretical predictions (lines) is very good within the range of validity of the computational method. Dotted symbols correspond to midtime profiles obtained from end-time statistics (see text).

nonical equilibrium, i.e., for a one-dimensional closed diffusive system on a ring [4,18,19]. In this case the optimal profiles remain flat and current fluctuations are Gaussian up to a critical current value, at which profiles become time dependent (traveling waves) [19]. Hence current statistics can differ considerably depending on the particular equilibrium ensemble at hand, despite their equivalence for average quantities in the thermodynamic limit. Finally, notice also that equilibrium optimal profiles are symmetric with respect to $x=1/2$, as expected since $T_L=T_R$.

For small enough current fluctuations around the average, $q \approx \langle q \rangle$ with $\langle q \rangle = 1/2$ for $T_L=2$ and $T_R=1$, BD theory predicts the limiting behavior

$$\frac{T_q(x) - T_{st}(x)}{2q - 1} = \frac{1}{7}x(1-x)(5-x) + \mathcal{O}(2q - 1). \quad (22)$$

Fig. 6 confirms this scaling for $T_q(x)$ and many different small current fluctuations around the average. In particular, it shows data obtained both from standard simulations (see Appendix B) and using the advanced method of Ref. [20].

It is also interesting to study the statistics of configurations both during a large deviation event and at the end. They differ due to final transient effects which decay exponentially fast, but a connection exists between both regimes which

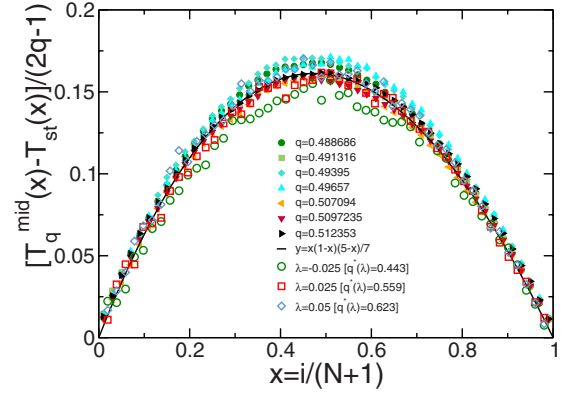


FIG. 6. (Color online) Scaling plot of the excess profiles for small current fluctuations. Here we plot results obtained from standard simulations (solid symbols) and the advanced algorithm of Ref. [20] (open symbols), as well as the theoretical prediction (line).

highlights the symmetry of midtime statistics resulting from the reversibility of microscopic dynamics (symmetry akin to the fluctuation relation). Reversibility in stochastic dynamics stems from the condition of local detailed balance [13], which implies a relation between the forward modified dynamics for a current fluctuation, $\tilde{U}(\lambda)$, and the time reversed modified dynamics for the negative fluctuation, $\tilde{U}^T(-\lambda - \mathcal{E})$, see Eq. (D6) in Appendix D. This can be used to derive a relation between midtime and endtime statistics (see Appendix D),

$$P_\lambda^{\text{mid}}(C) = A \frac{P_\lambda^{\text{end}}(C) P_{-\lambda - \mathcal{E}}^{\text{end}}(C)}{p_C^{\text{eq}}}, \quad (23)$$

Here $P_\lambda^{\text{end}}(C)$ [respectively, $P_\lambda^{\text{mid}}(C)$] is the probability of configuration C at the end (respectively, at intermediate times) of a large deviation event with current-conjugate parameter λ , and $p_C^{\text{eff}} = \exp[-\sum_{i=1}^N \beta_i e_i]$ is an effective weight for configuration $C = \{e_i, i = 1 \dots N\}$, with $\beta_i = T_L^{-1} + \mathcal{E} \frac{i-1}{N-1}$, while A is a normalization constant. As for Eq. (2), the above relation is valid only in the appropriate asymptotic (long-time) limit. Eq. (23) implies that configurations with a significant contribution to the average profile at intermediate times are those with an important probabilistic weight at the end of both the large deviation event and its time-reversed process. An important consequence of Eq. (23) is hence that $P_\lambda^{\text{mid}}(C) = P_{-\lambda - \mathcal{E}}^{\text{mid}}(C)$ or equivalently $P_q^{\text{mid}}(C) = P_{-q}^{\text{mid}}(C)$, so midtime statistics does not depend on the sign of the current. This implies in particular that $T_q^{\text{mid}}(x) = T_{-q}^{\text{mid}}(x)$, but also that all higher-order profiles $\langle e^n(x) \rangle_q$ and spatial correlations $\langle e^n(x_1) \dots e^n(x_m) \rangle_q$ are independent of the current sign $\forall n, m$.

The above connection allows us to relate midtime and endtime profiles for a given current fluctuation. For that we need additionally a LE hypothesis, i.e., we now assume that spatial correlations at the end of a large deviation event are weak enough so the distribution $P_\lambda^{\text{end}}(C)$ can be approximately factorized, $P_\lambda^{\text{end}}(C) \approx \prod_{i=1}^N P_\lambda^{\text{end}}(e_i)$. In this way we obtain a local equilibrium picture with local temperature parameter $T_\lambda^{\text{end}}(x = \frac{i}{N+1})$. This hypothesis can be numerically

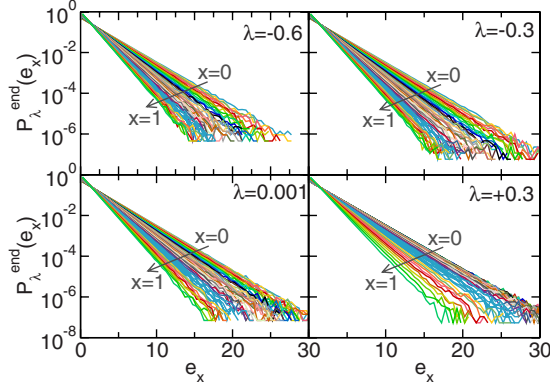


FIG. 7. (Color online) Semilog plot of local energy histograms along the chain for different values of λ at the end of the large deviation event. Notice that, in all cases, energy distributions are very close to exponential.

justified by measuring, at the end of the large deviation event, local energy distributions along the chain for different values of λ , see Fig. 7. In all cases the distribution is compatible with local equilibrium to a large degree of accuracy. Using Eq. (23) and the LE hypothesis we thus find

$$T_{\lambda}^{\text{mid}}(x) = \frac{T_{\lambda}^{\text{end}}(x)T_{-\lambda-\varepsilon}^{\text{end}}(x)}{T_{\lambda}^{\text{end}}(x) + T_{-\lambda-\varepsilon}^{\text{end}}(x) - \beta_x T_{\lambda}^{\text{end}}(x)T_{-\lambda-\varepsilon}^{\text{end}}(x)}. \quad (24)$$

Figure 8 shows endtime profiles $T_{\lambda}^{\text{end}}(x)$ measured both in equilibrium (bottom) and nonequilibrium (top) conditions for different values of λ . These profiles are clearly asymmetric upon current inversion, $T_{\lambda}^{\text{end}}(x) \neq T_{-\lambda-\varepsilon}^{\text{end}}(x)$, and most interestingly they show boundary resistance which depends on λ and on the particular definition for the elementary current, see [22]. In the equilibrium case the symmetry $T_q^{\text{end}}(x) = T_{-q}^{\text{end}}(1-x)$ resulting from the reflection invariance in this case ($T_L = T_R$) is apparent in Fig. 8 (bottom). Figure 5 also shows midtime profiles obtained from the measured $T_{\lambda}^{\text{end}}(x)$ via Eq. (24). The agreement with theoretical predictions and direct measurements of midtime profiles is good, though discrepancies appear for large enough current fluctuations, pointing out that corrections to LE are weak but increase for large current deviations. We show below that these corrections are also present for small current fluctuations and can be measured.

We can now explore physics beyond the additivity conjecture by studying fluctuations of the system total energy, $e(C) = N^{-1} \sum_{i=1}^N e_i$, for which current theoretical approaches cannot offer any general prediction. An exact result by Bertini, Gabrielli, and Lebowitz (BGL) [27] predicts that

$$m_2(e) = m_2^{LE}(e) + \frac{1}{12}(T_L - T_R)^2, \quad (25)$$

where $m_2(e) = N(\langle e^2 \rangle - \langle e \rangle^2)$ is the variance of the total energy in the NESS, m_2^{LE} is the variance assuming a LE product measure, and the last term reflects the correction to LE due to weak long-range correlations in the NESS [27], which in this case results in the enhancement of energy fluctuations. Corrections to LE vanish in the thermodynamic limit but extend

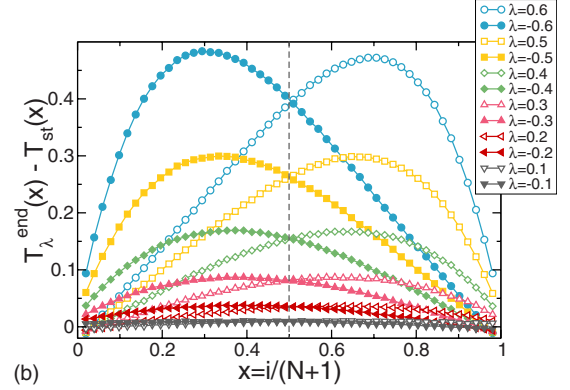
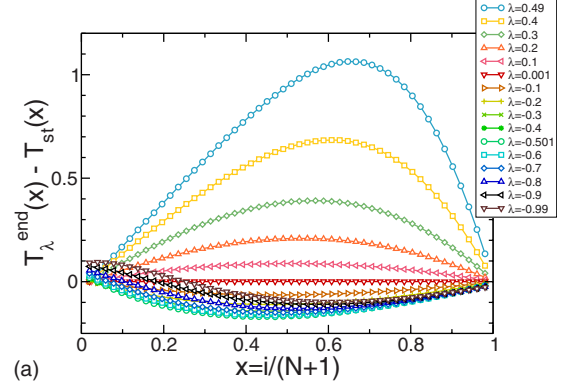


FIG. 8. (Color online) Excess temperature profiles measured at the end of the large deviation event for different values of λ , both in the presence of a temperature gradient (top), $T_L = 2$ and $T_R = 1$, and in canonical equilibrium (bottom), $T_L = 1.5 = T_R$. Notice that in all cases $T_{\lambda}^{\text{end}}(x) \neq T_{-\lambda-\varepsilon}^{\text{end}}(x)$, although for the equilibrium case the symmetry $T_{\lambda}^{\text{end}}(x) = T_{-\lambda}^{\text{end}}(1-x)$ is apparent.

over macroscopic distances (of order N), giving rise in general to a nonlocal current LDF [27]. In our case,

$$m_2^{LE} = \frac{1}{3}(T_L^2 + T_L T_R + T_R^2) = \frac{7}{3} \approx 2.3333, \quad (26)$$

while $m_2 = 29/12 \approx 2.4166$. Figure 9 plots $m_2(e, \lambda) = N[\langle e^2 \rangle_{\lambda} - \langle e \rangle_{\lambda}^2]$ as a function of λ for both equilibrium and nonequilibrium conditions, showing a nontrivial, interesting structure which both BD theory and HFT cannot explain. One might obtain a theoretical prediction for $m_2(e, \lambda)$ by supplementing the additivity principle with a LE hypothesis,

$$P_{\lambda}(C) \propto \prod_{i=1}^N \exp\left[-\frac{e_i}{T_{\lambda}\left(\frac{i}{N+1}\right)}\right], \quad (27)$$

which results in

$$m_2^{LE}(e, \lambda) = \int_0^1 T_{\lambda}(x)^2 dx. \quad (28)$$

This prediction agrees qualitatively with the observed behavior, though fine quantitative differences are apparent, see Fig. 9, as otherwise expected. In particular we find that, out of equilibrium, $m_2^{LE}(e, 0) \approx 2.33$ as corresponds to a LE picture and in contrast to the measured value $m_2(e, 0) = 2.422(14)$ in

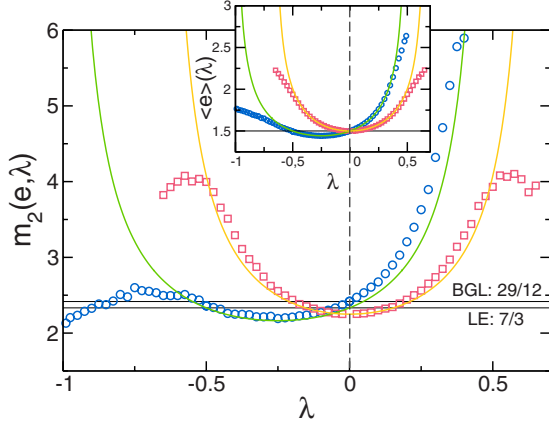


FIG. 9. (Color online) Fluctuations of the total energy per site versus λ for both equilibrium (\square , $T_L=1.5=T_R$) and nonequilibrium (\circ , $T_L=2$, and $T_R=1$) conditions. The lines stand for predictions based on the additivity principle plus a local equilibrium hypothesis. Inset: average energy per site and BD prediction in both situations. Notice that, as before, deviations observed in all cases for extreme current fluctuations are spurious and result from known limitations of the method of Ref. [20].

Fig. 9, which compares nicely with the exact BGL result 29/12 (recall that $\lambda=0$ corresponds to $q=\langle q \rangle$). This shows that, even though LE is a sound numerical hypothesis to obtain $T_\lambda(x)$ from endtime statistics for small and moderate current fluctuations, see Fig. 5 and Eq. (24), corrections to LE become apparent at the fluctuating level even for small current fluctuations. This is also shown in Fig. 15 in Appendix B, where fluctuations of the total energy under nonequilibrium conditions are studied in standard simulations. On the other hand, in the canonical equilibrium case ($T_L=1.5=T_R$) no corrections to LE show up for $\lambda=0$ (i.e., for $q=\langle q \rangle=0$), as expected. However, as soon as $q \neq \langle q \rangle$, deviations of $m_2(e, \lambda)$ from the LE prediction $m_2^{LE}(e, \lambda)$ are observed, thus showing that local equilibrium is broken at the fluctuating level even for equal bath temperatures.

Finally, the inset to Fig. 9 shows the average energy per site as a function of λ , together with the prediction based on the additivity principle, $\langle e \rangle_\lambda = \int_0^1 T_\lambda(x) dx$. Agreement is again very good in the large range of currents explored. It is interesting to note that in order to sustain a current fluctuation above the average, $q > \langle q \rangle$ or equivalently $\lambda > 0$, the nonequilibrium system ($T_L > T_R$) has always a larger average energy than its equilibrium counterpart ($T_L = T_R$), while the reverse holds for current fluctuations below the average, $q < \langle q \rangle$, see inset to Fig. 9.

V. JOINT FLUCTUATIONS OF THE CURRENT AND THE PROFILE

For long but finite times, the profile associated to a given current fluctuation is subject to fluctuations itself [14,28,29]. These joint fluctuations of the current and the profile are again not described by the additivity principle, but we may study them by extending the additivity conjecture. In this way, we now assume that the probability to find a time-

integrated current q/N and a temperature profile $\bar{T}_q(x)$ after averaging for a long but finite-time t can be written as

$$W_N \left[\frac{q}{N}, \bar{T}_q(x); t \right] \simeq \exp \left(+ \frac{t}{N} \bar{\mathcal{G}}[q, \bar{T}_q(x)] \right), \quad (29)$$

where now

$$\bar{\mathcal{G}}[q, \bar{T}_q(x)] = - \int_0^1 \frac{[q + \kappa[\bar{T}_q(x)]\bar{T}'_q(x)]^2}{2\sigma[\bar{T}_q(x)]} dx. \quad (30)$$

Notice that here no minimization with respect to temperature profiles is performed, see Eq. (4). In this scheme the profile obeying Eq. (5), i.e., the one which minimizes the functional $\bar{\mathcal{G}}$, is the *classical* profile $T_q(x)$. For a given q value we can make a perturbation of $\bar{T}_q(x)$ around its classical value,

$$\bar{T}_q(x) = T_q(x) + \eta_q(x). \quad (31)$$

For large enough t , the joint probability of q and $\eta_q(x)$ can be written as

$$\frac{W_N[q, \eta_q(x); t]}{P_N(q; t)} \simeq \exp \left[- \frac{1}{2} \int dx dy A_q(x, y) \eta_q(x) \eta_q(y) \right] \quad (32)$$

where $P_N(q, t)$ is defined in Eq. (1), together with Eqs. (4) and (5). The integral kernel is

$$\frac{N}{t} A_q(x, y) = \left[\frac{1}{2T_q^3} \frac{dT_q}{dx} \frac{d}{dx} - \frac{1}{4T_q^2} \frac{d^2}{dx^2} - 2 \frac{K(q)q^2}{T_q^2} \right] \delta(x - y). \quad (33)$$

One can show that the kernel $A_q(x, y)$ is symmetric with respect to x and y . In order to check the above joint probability distribution, we studied the observable

$$\langle \bar{T}_q^2(x) \rangle - T_q^2(x) = \langle \eta_q^2(x) \rangle = A_q^{-1}(x, x), \quad (34)$$

where

$$A_q^{-1}(x, y) = \sum_{n=1}^{\infty} \phi_n^{-1} v_n(x; q) v_n(y; q), \quad (35)$$

and $v_n(x; q)$ and ϕ_n are the eigenvectors and eigenvalues of kernel A_q , respectively,

$$\int dx A_q(x, y) v_n(x; q) = \phi_n v_n(y; q), \quad (36)$$

with $v_n(0; q) = 0 = v_n(1; q)$. For $q = \langle q \rangle = 1/2$ (nonequilibrium conditions, $T_L = 2$, $T_R = 1$) we were able to solve the eigenvalue equation, yielding

$$v_n(x; 1/2) = B T_{1/2}(x)^{3/2} \{ J_{-3/4}(\bar{\phi}_n T_L^2) J_{3/4}[\bar{\phi}_n T_{1/2}(x)^2] - J_{3/4}(\bar{\phi}_n T_L^2) J_{-3/4}[\bar{\phi}_n T_{1/2}(x)^2] \}, \quad (37)$$

where $\bar{\phi}_n = (\phi_n N/t)^{1/2} / (T_L - T_R)$, J 's are the Bessel functions and B is the normalization factor that is obtained by requiring

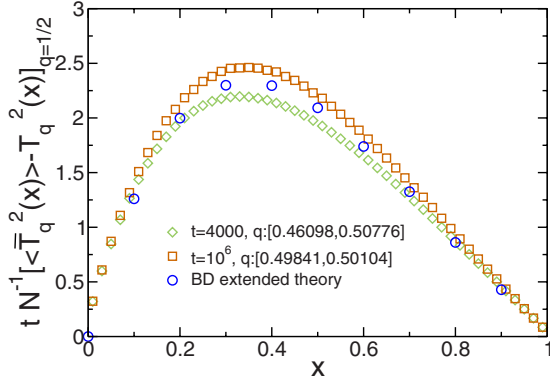


FIG. 10. (Color online) Finite-time profile fluctuations $\langle \eta_q^2(x) \rangle$. Blue circles are the numerical evaluation of the series expansion from the extended BD theory (see text). Diamonds and squares represent standard simulation results for q 's in the interval shown in the figure, $N=50$ and $t=4000$ and $t=10^6$, respectively.

$$\int_0^1 dx v_n(x; 1/2)^2 = 1. \quad (38)$$

Finally, ϕ_n are the solutions of the equation

$$J_{3/4}(\overline{\phi}_n T_L^2) J_{-3/4}(\overline{\phi}_n T_R^2) = J_{-3/4}(\overline{\phi}_n T_L^2) J_{3/4}(\overline{\phi}_n T_R^2). \quad (39)$$

We compare in Fig. 10 the numerical evaluation of $A_{1/2}^{-1}(x, x)$ (where we have computed 10, 15, 30, 50, 100, and 200 terms of the series and extrapolated to $n \rightarrow \infty$) with the standard simulation results for $N=50$ and $t=4000$ and $t=10^6$. We observe a good agreement between theoretical and simulation results. Notice that we average over a small q window around $q=1/2$ in simulations. These results show that the BD functional $\overline{\mathcal{Q}}[q, \overline{T}_q(x)]$ of Eq. (30) contains the essential information on the joint fluctuations of the current and the average profile, extending the validity of the additivity principle to finite-time situations.

VI. CONCLUSIONS

In this paper, we have confirmed via extensive computer simulations the validity of the additivity principle for current fluctuations in the 1D Kipnis-Marchioro-Pressuti model of energy transport. In particular, we found that the current distribution shows a Gaussian regime for small current fluctuations and non-Gaussian, exponential tails for large deviations of the current such that in all cases the fluctuation relation holds. We verified the existence of a well-defined temperature profile associated to a given current fluctuation, different from the steady-state profile and invariant under current reversal. In addition, we extended the additivity conjecture to joint current-profile fluctuations.

Our results thus strongly support the additivity hypothesis as an important tool to understand current statistics in diffusive systems, opening the door to a general approach to a large class of nonequilibrium phenomena based on few simple principles. Our results do not discard however the possible breakdown of additivity for extreme current fluctuations due to the onset of time-dependent profiles although we

stress that this scenario is not observed here and would affect only the far tails of the current distribution. In this respect it would be interesting to study the KMP model on a ring, for which a dynamic phase transition to time-dependent profiles is expected [4, 18, 19]. Also interesting is the possible extension of the additivity principle to low-dimensional systems with anomalous, nondiffusive transport properties [11], or to systems with several conserved fields or in higher dimensions.

ACKNOWLEDGMENTS

We thank B. Derrida, J. L. Lebowitz, V. Lecomte, and J. Tailleur for illuminating discussions and comments. Financial support from Spanish project No. FIS2009-08451, AFOSR Grant No. AF-FA-9550-04-4-22910, and University of Granada is also acknowledged.

APPENDIX A: PREDICTIONS USING THE ADDITIVITY PRINCIPLE

In this appendix, we use the KMP model values for $\kappa(T)=\frac{1}{2}$ and $\sigma(T)=T^2$ in Eqs. (4) and (5) to derive explicit predictions for the current large deviation function in this model and the associated optimal temperature profiles. In what follows we assume $T_L > T_R$ without loss of generality. The differential equation for the optimal profile in the KMP case reads

$$\left(\frac{dT_q(x)}{dx} \right)^2 = 4q^2 \{1 + 2T_q^2(x)K(q^2)\}. \quad (A1)$$

Here two different scenarios appear. On one hand, for large enough $K(q^2)$ the right-hand side of Eq. (A1) does not vanish $\forall x \in [0, 1]$ and the resulting profile is monotone. In this case, the optimal profile obeys

$$\frac{dT_q(x)}{dx} = -2|q| \sqrt{1 + 2T_q^2(x)K(q^2)}. \quad (A2)$$

On the other hand, for $K(q^2) < 0$ the rhs of Eq. (A1) may vanish at some points, resulting in a $T_q(x)$ that is nonmonotone and takes a unique value $T_q^* \equiv \sqrt{-1/2K(q^2)}$ in the extrema. Notice that the right-hand side of the above equation may be written in this case as $4q^2[1 - (T_q(x)/T_q^*)^2]$. It is then clear that, if nonmonotone, the profile $T_q(x)$ can only have a single maximum $T_q(x^*) = T_q^*$ because: (i) $T_q(x) \leq T_q^* \forall x \in [0, 1]$ for the profile to be a real function and (ii) several maxima are not possible because they should be separated by a minimum, which is not allowed because of (i). In this case

$$\frac{dT_q(x)}{dx} = \begin{cases} +2|q| \sqrt{1 - \left(\frac{T_q(x)}{T_q^*}\right)^2}, & x < x^* \\ -2|q| \sqrt{1 - \left(\frac{T_q(x)}{T_q^*}\right)^2}, & x > x^* \end{cases}. \quad (A3)$$

This leaves us with two separated regimes for current fluctuations, with the crossover happening for $|q| = \frac{T_L}{2}$

$[\frac{\pi}{2} - \sin^{-1}(\frac{T_R}{T_L})]$. This crossover current may be obtained from Eq. (A13) below by letting $T_q^* \rightarrow T_L$.

1. Region I: $|q| < \frac{T_L}{2} [\frac{\pi}{2} - \sin^{-1}(\frac{T_R}{T_L})]$

In this region the optimal profile $T_q(x)$ is monotone in $x \in [0, 1]$. Equation (8) then leads to

$$\mathcal{G}(q) = \frac{q}{2} \left(\frac{1}{T_R} - \frac{1}{T_L} \right) - q^2 K(q^2) + \frac{|q|}{2} \left(\frac{\sqrt{1 + 2K(q^2)T_L^2}}{T_L} - \frac{\sqrt{1 + 2K(q^2)T_R^2}}{T_R} \right), \quad (\text{A4})$$

where $K(q^2)$ is a constant defined by the boundary conditions. The optimal temperature profile $T_q(x)$ in this regime is the solution of the following implicit equation:

$$2x|q| = \frac{1}{\sqrt{2K(q^2)}} \ln \left[\frac{T_L + \sqrt{T_L^2 + \frac{1}{2K(q^2)}}}{T_q(x) + \sqrt{T_q(x)^2 + \frac{1}{2K(q^2)}}} \right], \quad (\text{A5})$$

whenever $K(q^2) > 0$, or rather

$$2x|q| = \frac{\sin^{-1}[\sqrt{-2K(q^2)T_L}] - \sin^{-1}[\sqrt{-2K(q^2)T_q(x)}]}{\sqrt{-2K(q^2)}}, \quad (\text{A6})$$

in the case $-\frac{1}{2T_L^2} < K(q^2) < 0$, see Eq. (A2). Making $x=1$ and $T_q(x=1)=T_R$ here, we obtain the implicit equation for the constant $K(q^2)$.

Sometimes it is interesting to work with the Legendre transform of the large deviation function, $\mu(\lambda) = N^{-1} \max_q [\mathcal{G}(q) + \lambda q] = \mathcal{G}(q_o) + \lambda q_o$, with $q_o(\lambda)$ given by $\partial_q \mathcal{G}(q_o) + \lambda = 0$, and where now $-T_R^{-1} < \lambda < T_L^{-1}$. It then follows

$$\mu(\lambda) = -\frac{K(\lambda)}{N} [q_o(\lambda)]^2, \quad (\text{A7})$$

where

$$2|q_o(\lambda)| = \frac{1}{\sqrt{2K(\lambda)}} \ln \left[\frac{T_L + \sqrt{T_L^2 + \frac{1}{2K(\lambda)}}}{T_R + \sqrt{T_R^2 + \frac{1}{2K(\lambda)}}} \right], \quad (\text{A8})$$

when $K(\lambda) > 0$, or instead

$$2|q_o(\lambda)| = \frac{\sin^{-1}[\sqrt{-2K(\lambda)T_L}] - \sin^{-1}[\sqrt{-2K(\lambda)T_R}]}{\sqrt{-2K(\lambda)}}, \quad (\text{A9})$$

in the case $-\frac{1}{2T_L^2} < K(\lambda) < 0$, and the constant $K(\lambda) \equiv K[q_o(\lambda)^2]$ is solution of the implicit equation

$$\lambda = -\frac{1}{2} \left(\frac{1}{T_R} - \frac{1}{T_L} \right) + \frac{\text{sgn}[q_o(\lambda)]}{2} \times \left[\frac{\sqrt{1 + 2K(\lambda)T_R^2}}{T_R} - \frac{\sqrt{1 + 2K(\lambda)T_L^2}}{T_L} \right]. \quad (\text{A10})$$

The optimal profile for a given λ is just $T_\lambda(x) = T_{q_o(\lambda)}(x)$. In λ space, monotone profiles are expected for $\lambda \in [\lambda_-, \lambda_+]$ where $\lambda_\pm = -(T_R^{-1} - T_L^{-1})/2 \pm \sqrt{1 - (T_R/T_L)^2}/(2T_R)$.

2. Region II: $|q| > \frac{T_L}{2} [\frac{\pi}{2} - \sin^{-1}(\frac{T_R}{T_L})]$

In this case the optimal profile is nonmonotone with a single maximum $T_q^* = T_q(x^*)$, see Eq. (A3). In this regime $K(q^2) < 0$, and $T_q^* = 1/\sqrt{-2K(q^2)}$. It follows

$$\mathcal{G}(q) = \frac{|q|}{4T_q^*} \left[\pi - \sin^{-1}\left(\frac{T_R}{T_q^*}\right) - \sin^{-1}\left(\frac{T_L}{T_q^*}\right) \right] + \frac{q}{2} \left(\frac{1}{T_R} - \frac{1}{T_L} \right) - \frac{|q|}{2} \frac{\sqrt{1 - \left(\frac{T_R}{T_q^*}\right)^2}}{T_R} - \frac{|q|}{2} \frac{\sqrt{1 - \left(\frac{T_L}{T_q^*}\right)^2}}{T_L}. \quad (\text{A11})$$

The optimal profile solution of Eq. (A3) is given by

$$x = \begin{cases} \frac{T_q^*}{2|q|} \left[\sin^{-1}\left(\frac{T(x)}{T_q^*}\right) - \sin^{-1}\left(\frac{T_L}{T_q^*}\right) \right], & x < x^* \\ 1 + \frac{T_q^*}{2|q|} \left[\sin^{-1}\left(\frac{T_R}{T_q^*}\right) - \sin^{-1}\left(\frac{T(x)}{T_q^*}\right) \right], & x > x^* \end{cases}. \quad (\text{A12})$$

At the location of the profile maximum, $x=x^*$, both branches in the above equation must coincide and this condition provides equations for both x^* and T_q^*

$$|q| = \frac{T_q^*}{2} \left[\pi - \sin^{-1}\left(\frac{T_L}{T_q^*}\right) - \sin^{-1}\left(\frac{T_R}{T_q^*}\right) \right], \quad (\text{A13})$$

$$x^* = \frac{\frac{\pi}{2} - \sin^{-1}\left(\frac{T_L}{T_q^*}\right)}{\pi - \sin^{-1}\left(\frac{T_L}{T_q^*}\right) - \sin^{-1}\left(\frac{T_R}{T_q^*}\right)}. \quad (\text{A14})$$

As in Regime I, we find for the Legendre transform $\mu(\lambda) = -N^{-1}K(\lambda)q_o(\lambda)^2 = (2N)^{-1}[q_o(\lambda)/T_\lambda^*]^2$, with $q_o(\lambda)$ defined in Eq. (A13), $T_\lambda^* \equiv T_{q_o(\lambda)}^*$, and λ given as in Eq. (A10) but with the notation change $K(\lambda) \rightarrow -1/[2(T_\lambda^*)^2]$. Nonmonotone profiles are then expected for $\lambda \in [-T_R^{-1}, \lambda_-] \cup [\lambda_+, T_L^{-1}]$.

Figure 1 in the main text shows the predicted $\mathcal{G}(q)$ for the KMP model. Notice that the large deviation function is zero for $q = \langle q \rangle = (T_L - T_R)/2$ and negative elsewhere. Moreover, for large current fluctuations it decays linearly, $\mathcal{G}(q) \rightarrow -q/T_{R,L}$ for $|q| \gg \langle q \rangle$. For a small positive current fluctuation, $K(q^2) \rightarrow 0$ and

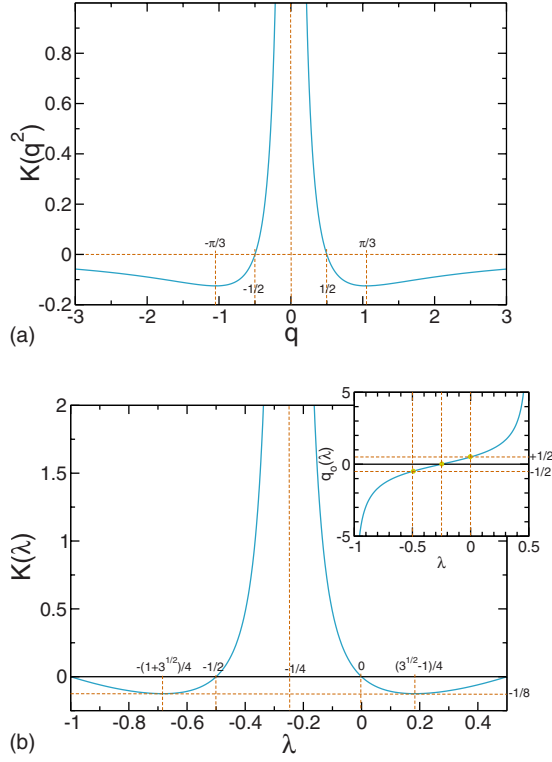


FIG. 11. (Color online) Top panel: Constant K as a function of q for $T_R=2$ and $T_L=1$. Bottom panel: the same constant as a function of λ . The inset shows the current q_o conjugated to λ .

$$\mathcal{G}(q) \approx -\frac{3\left(|q| - \frac{T_L - T_R}{2}\right)^2}{2(T_L^2 + T_L T_R + T_R^2)}, \quad (\text{A15})$$

which translates into

$$\mu(\lambda) \approx \frac{\lambda}{2N} \left[(T_L - T_R) + \frac{\lambda}{3}(T_L^2 + T_L T_R + T_R^2) \right], \quad (\text{A16})$$

for the Legendre transform. Therefore the probability of small current fluctuations is Gaussian in q while it becomes exponential for large enough deviations from the average, see Eq. (1). It is easy to show that the Gallavotti-Cohen symmetry holds, with

$$\mathcal{G}(q) - \mathcal{G}(-q) = 2q \int_{T_R}^{T_L} \frac{\kappa(T)}{\sigma(T)} = q \left(\frac{1}{T_R} - \frac{1}{T_L} \right), \quad (\text{A17})$$

or equivalently

$$\mu(\lambda) = \mu(-\lambda - \mathcal{E}), \quad (\text{A18})$$

with $\mathcal{E} \equiv (T_R^{-1} - T_L^{-1})$. Figure 2 in the main text shows the optimal temperature profiles for different current deviations. Notice that the optimal profile is independent of the sign of the current, i.e., $T_q(x) = T_{-q}(x)$, reflecting the time-reversal symmetry of microscopic dynamics [12,13]. Finally, Fig. 11 shows, for information purposes, the integration constant K as a function of both q and λ , as well as λ dependence of $q_o(\lambda)$.

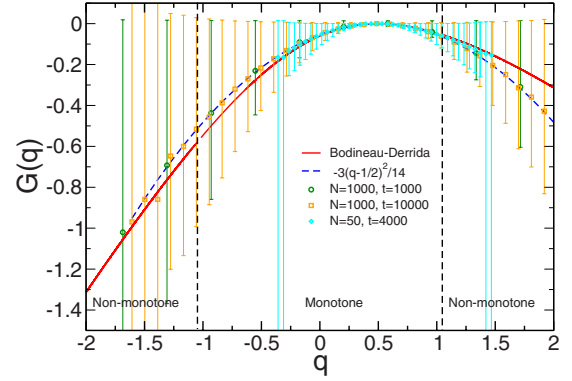


FIG. 12. (Color online) $\mathcal{G}(q)$ measured for different system sizes N and measurement times t (see text), with $T_L=2$ and $T_R=1$ fixed. Lines correspond to BD theory and the Gaussian approximation.

APPENDIX B: STANDARD SIMULATIONS

In order to see how far standard simulations can go in evaluating current large fluctuations, and to crosscheck our results with the more advanced simulation methods described in Appendix C, we performed a large number of steady-state simulations of long duration t , with $T_L=2$ and $T_R=1$, measuring the total time-integrated current $Q_t = q t$ and accumulating statistics for q . Figure 12 shows the measured $\mathcal{G}(q)$ obtained for different system sizes N and durations t . Our simulations for $N=1000$ and different times $t < N^2$ follow closely the Gaussian law $\mathcal{G}(q) \approx -3(q-1/2)^2/14$ obtained from the first two moments prescribed by the additivity principle in this case, namely,

$$m_1 = \frac{T_L - T_R}{2},$$

$$m_2 = \frac{T_L^2 + T_L T_R + T_R^2}{3}.$$

This Gaussian behavior is expected for small fluctuations around the average current, see Eq. (A15), but deviations away from Gaussianity should be already observed in the current range studied, see the theoretical prediction. In particular, the theoretical $\mathcal{G}(q)$ implies a nonzero third central moment, but we have not found numerical evidence of such a deviation for $N=1000$. This lack of structure stems from the relatively short duration of the simulations for $N=1000$, i.e., our results are not in the diffusive regime ($t < N^2$ here) and therefore we have not reached the asymptotic behavior.

We performed two set of simulations in the diffusive regime $t > N^2$, namely, $N=50$ with $t=10^6$ and 4000. In the first case there were no events outside the current interval $q \in [0.45, 0.56]$, for which the BD prediction is numerically indistinguishable from the Gaussian one. On the other hand, the case $N=50$ and $t=4000$ shows systematic deviations from Gaussian behavior, seemingly compatible with BD theory, see Fig. 12. However, large error bars resulting from the difficulty of gathering statistics in this rare-fluctuation regime do not allow us to exclude Gaussian behavior. In this

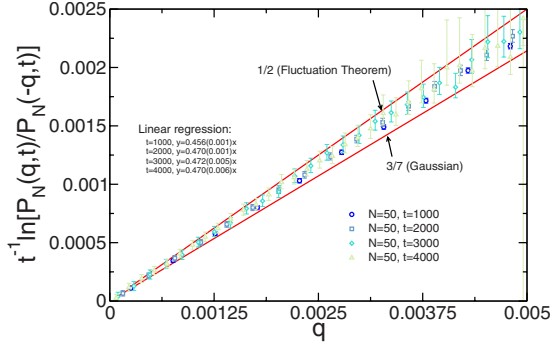


FIG. 13. (Color online) Test of the fluctuation theorem of Gallavotti and Cohen. Here we explore $N=50$ and different maximum times t . If BD theory holds a slope $1/2$ is expected, while Gaussian behavior involves a slope $3/7$.

way, standard simulation results are inconclusive, as otherwise expected, and the more refined simulation techniques of Appendix C are called for.

We also tested the Gallavotti-Cohen relation in standard simulations for our system. This symmetry implies that

$$\lim_{t \rightarrow \infty} \frac{1}{t} \ln \frac{P_N(q, T_L, T_R, t)}{P_N(-q, T_L, T_R, t)} = \mathcal{E}q, \quad (\text{B1})$$

where $\mathcal{E} = (T_R^{-1} - T_L^{-1}) = 1/2$ in this case. Notice that if we assume $P_N(q, T_L, T_R; t)$ to be Gaussian with the moments defined above, then one expects $\mathcal{E} = 3/7$. Figure 13 shows the above quotient as measured for $N=50$ and different values of t . It shows a systematic deviation from Gaussian behavior which increases with t . However, we do not see clearly $\mathcal{E} = 1/2$ and this means again that our standard simulations are still far from the true asymptotic regime in t .

Another prediction of the additivity principle concerns the existence of an optimal temperature profile that the system adopts in order to facilitate a given current fluctuation. We measured in standard simulations the average energy profile during a current large deviation event, obtaining the results shown in Fig. 14. As above, only for small current fluctuations we could gather enough statistics for the data to be

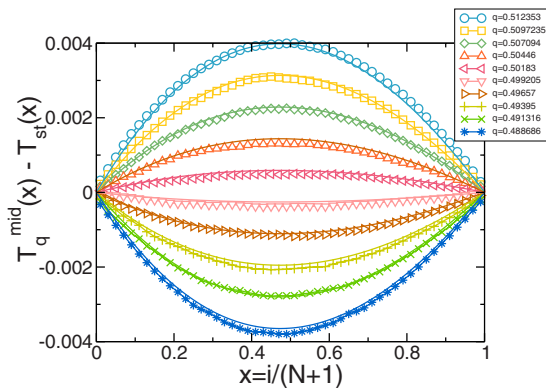


FIG. 14. (Color online) Excess average profiles during a large deviation event for small current fluctuations, as measured in standard simulations. Agreement with BD theoretical predictions (lines) is excellent.

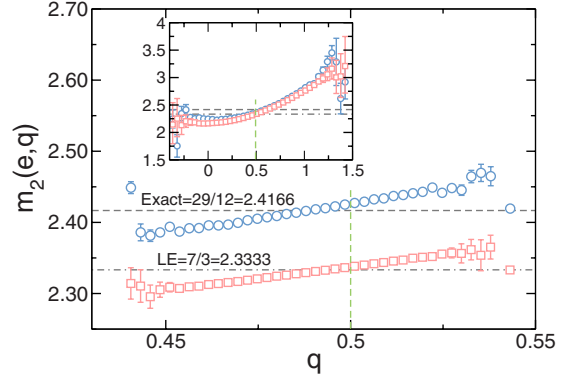


FIG. 15. (Color online) Fluctuations of total energy vs q measured in standard simulations for $t=10^6$ (○) and LE results (□). Inset: similar results for $t=4000$. Notice the nontrivial structure.

significant. In any case, the theoretical optimal profiles compare nicely with data, confirming the existence of a well-defined temperature profile for each current deviation.

We also measured the fluctuations of the total energy in standard simulations. Figure 15 shows our results in this case. In particular, we measured $m_2(e) = 2.4(1)$ for $N=50$ and a maximum time $t=4000$ and $m_2(e) = 2.42(2)$ for $t=10^6$, in agreement with Eq. (26). This figure also shows $m_2(e, q)$ and $m_2^{LE}(e, q)$ build from simulation data for $T_q(x)$. As in Fig. 9, we see a clear deviation from local equilibrium and a well defined structure not predicted by BD theory. Notice that, again, values of $m_2(e, q)$ for $q=1/2$ coincide with the expected average values with no current constraint. The data shown in this figure agree nicely with those measured with the advanced technique in the studied range, see Fig. 9.

APPENDIX C: EVALUATION OF LARGE-DEVIATION FUNCTIONS

Large deviation functions are very hard to measure in experiments or simulations because they involve by definition exponentially unlikely events, see Eq. (1). Recently, Giardinà, Kurchan, and Peliti [20] have introduced an efficient algorithm to measure the probability of a large deviation for observables such as the current or density in stochastic many-particle systems. The algorithm is based on a modification of the underlying stochastic dynamics so that the rare events responsible of the large deviation are no longer rare and it has been extended for systems with continuous-time stochastic dynamics [21]. Let $U_{C'C}$ be the transition rate from configuration C to C' . The probability of measuring a time-integrated current Q_t after a time t starting from a configuration C_0 can be written as

$$P(Q_t, t; C_0) = \sum_{C_t \dots C_1} U_{C_t C_{t-1}} \dots U_{C_1 C_0} \delta \left(Q_t - \sum_{k=0}^{t-1} J_{C_{k+1} C_k} \right), \quad (\text{C1})$$

where $J_{C'C}$ is the elementary current involved in the transition $C \rightarrow C'$. For long times we expect the information on the initial state C_0 to be lost, $P(Q_t, t; C_0) \rightarrow P(Q_t, t)$. In this limit

$P(Q_t, t)$ obeys the usual large deviation principle $P(Q_t, t) \sim \exp[+t\mathcal{F}(q=Q_t/t)]$. In most cases it is convenient to work with the moment-generating function of the above distribution

$$\Pi(\lambda, t) = \sum_{Q_t} e^{\lambda Q_t} P(Q_t, t) = \sum_{C_r \dots C_1} U_{C_r C_{r-1}} \dots U_{C_1 C_0} e^{\lambda \sum_{k=0}^{r-1} c_{k+1} c_k}. \quad (\text{C2})$$

For long t , we have $\Pi(\lambda, t) \rightarrow \exp[+t\mu(\lambda)]$, with $\mu(\lambda) = \max_q [\mathcal{F}(q) + \lambda q]$. We can now define a modified dynamics, $\tilde{U}_{C'C} \equiv e^{\lambda C'C} U_{C'C}$, so

$$\Pi(\lambda, t) = \sum_{C_r \dots C_1} \tilde{U}_{C_r C_{r-1}} \dots \tilde{U}_{C_1 C_0}. \quad (\text{C3})$$

This dynamics is however not normalized, $\sum_{C'} \tilde{U}_{C'C} \neq 1$.

We now introduce Dirac's bra and ket notation, useful in the context of the quantum Hamiltonian formalism for the master equation [23,24], see also [20,25]. The idea is to assign to each system configuration C a vector $|C\rangle$ in phase space, which together with its transposed vector $\langle C|$, form an orthogonal basis of a complex space and its dual [23,24]. For instance, in the simpler case of systems with a finite number of available configurations (which is not the case for the KMP model), one could write $|C\rangle^T = \langle C| = (\dots 0 \dots 0, 1, 0 \dots 0 \dots)$, i.e., all components equal to zero except for the component corresponding to configuration C , which is 1. In this notation, $\tilde{U}_{C'C} = \langle C' | \tilde{U} | C \rangle$ and a probability distribution can be written as a probability vector

$$|P(t)\rangle = \sum_C P(C, t) |C\rangle,$$

where $P(C, t) = \langle C | P(t) \rangle$ with the scalar product $\langle C' | C \rangle = \delta_{C'C}$. If $\langle s | = (1 \dots 1)$, normalization then implies $\langle s | P(t) \rangle = 1$.

With the above notation, we can write the spectral decomposition $\tilde{U}(\lambda) = \sum_j e^{\Lambda_j(\lambda)} |\Lambda_j^R(\lambda)\rangle \langle \Lambda_j^L(\lambda)|$, where we assume that a complete biorthogonal basis of right and left eigenvectors for matrix \tilde{U} exists, $\tilde{U} |\Lambda_j^R(\lambda)\rangle = e^{\Lambda_j(\lambda)} |\Lambda_j^R(\lambda)\rangle$ and $\langle \Lambda_j^L(\lambda) | \tilde{U} = e^{\Lambda_j(\lambda)} \langle \Lambda_j^L(\lambda) |$. Denoting as $e^{\Lambda(\lambda)}$ the largest eigenvalue of $\tilde{U}(\lambda)$, with associated right and left eigenvectors $|\Lambda^R(\lambda)\rangle$ and $\langle \Lambda^L(\lambda) |$, respectively, and writing $\Pi(\lambda, t) = \sum_{C_t} \langle C_t | \tilde{U}^t | C_0 \rangle$, we find for long times

$$\Pi(\lambda, t) \xrightarrow{t \gg 1} e^{+t\Lambda(\lambda)} \langle \Lambda^L(\lambda) | C_0 \rangle \left(\sum_{C_t} \langle C_t | \Lambda^R(\lambda) \rangle \right). \quad (\text{C4})$$

In this way we have $\mu(\lambda) = \Lambda(\lambda)$, so the Legendre transform of the current LDF is given by the natural logarithm of the largest eigenvalue of $\tilde{U}(\lambda)$. In order to evaluate this eigenvalue, and given that dynamics \tilde{U} is not normalized, we introduce the exit rates $Y_C = \sum_{C'} \tilde{U}_{C'C}$ and define the normalized dynamics $U'_{C'C} \equiv Y_C^{-1} \tilde{U}_{C'C}$. Now

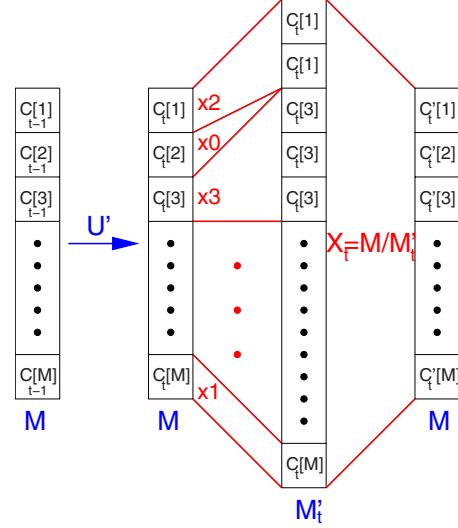


FIG. 16. (Color online) Sketch of the evolution and cloning of the copies during the evaluation of the large deviation function.

$$\Pi(\lambda, t) = \sum_{C_r \dots C_1} Y_{C_r} U'_{C_r C_{r-1}} \dots Y_{C_1} U'_{C_1 C_0}. \quad (\text{C5})$$

This sum over paths can be realized by considering an ensemble of $M \gg 1$ copies (or clones) of the system, evolving sequentially according to the following Monte Carlo scheme [20]:

(I) Each copy evolves independently according to modified normalized dynamics $U'_{C'C}$.

(II) Each copy $m \in [1, M]$ (in configuration $C_t[m]$ at time t) is cloned with rate $Y_{C_t[m]}$. This means that, for each copy $m \in [1, M]$, we generate a number $K_{C_t[m]} = \lfloor Y_{C_t[m]} \rfloor + 1$ of identical clones with probability $Y_{C_t[m]} - \lfloor Y_{C_t[m]} \rfloor$, or $K_{C_t[m]} = \lfloor Y_{C_t[m]} \rfloor$ otherwise (here $\lfloor x \rfloor$ represents the integer part of x). Note that if $K_{C_t[m]} = 0$ the copy may be killed and leave no offspring. This procedure gives rise to a total of $M'_t = \sum_{m=1}^M K_{C_t[m]}$ copies after cloning all of the original M copies.

(III) Once all copies evolve and clone, the total number of copies M'_t is sent back to M by a uniform cloning probability $X_t = M/M'_t$.

Figure 16 sketches this procedure. It then can be shown that, for long times, we recover $\mu(\lambda)$ via

$$\mu(\lambda) = -\frac{1}{t} \ln(X_t \dots X_0) \quad \text{for } t \gg 1. \quad (\text{C6})$$

To derive this expression, first consider the cloning dynamics above, but without keeping the total number of clones constant, i.e., forgetting about step III. In this case, for a given history $\{C_t, C_{t-1} \dots C_1, C_0\}$, the number $\mathcal{N}(C_t \dots C_0, t)$ of copies in configuration C_t at time t obeys $\mathcal{N}(C_t \dots C_0, t) = Y_{C_{t-1}} U'_{C_t C_{t-1}} \mathcal{N}(C_{t-1} \dots C_0, t-1)$, so that

$$\mathcal{N}(C_t \dots C_0, t) = Y_{C_{t-1}} U'_{C_t C_{t-1}} \dots Y_{C_0} U'_{C_1 C_0} \mathcal{N}(C_0, 0). \quad (\text{C7})$$

Summing over all histories of duration t , see Eq. (C5), we find that the average of the total number of clones at long

times shows exponential behavior, $\langle \mathcal{N}(t) \rangle = \sum_{C_t \dots C_1} \mathcal{N}(C_t \dots C_0, t) \sim \mathcal{N}(C_0, 0) \exp[+t\mu(\lambda)]$. Now, going back to step III above, when the fixed number of copies M is large enough, we have $X_t = \langle \mathcal{N}(t-1) \rangle / \langle \mathcal{N}(t) \rangle$ for the global cloning factors, so $X_t \dots X_1 = \mathcal{N}(C_0, 0) / \langle \mathcal{N}(t) \rangle$ and we recover expression (C6) for $\mu(\lambda)$.

In this paper, we used the above method to measure the current LDF for the Kipnis-Marchioro-Presutti model in one dimension, described in Sec. III. For this model the transition rate from a configuration $C = \{e_1 \dots e_N\}$ to another configuration $C'_y = \{e_1 \dots e'_y, e'_{y+1} \dots e'_N\}$, with $y \in [0, N]$ and the pair (e'_y, e'_{y+1}) defined as in Eqs. (18) and (19), can be written as

$$U_{C'_y C} = \begin{cases} (N+1)^{-1}, & y \in [1, N-1] \\ \frac{\beta_- e^{\beta_- e_1}}{N+1} E_1[\beta_- \max(e_1, e'_1)], & y = 0 \\ \frac{\beta_+ e^{\beta_+ e_N}}{N+1} E_1[\beta_+ \max(e_N, e'_N)], & y = N. \end{cases}$$

Here $E_1(x) = -\text{Ei}(-x)$, where $\text{Ei}(x)$ is the exponential integral function, or

$$E_1(x) = \int_x^\infty du \frac{e^{-u}}{u}. \quad (\text{C8})$$

It appears when integrating over all possible pairs $(p, \tilde{e}_{L,R})$ that can result on a given $e'_{1,N}$, respectively, see Eq. (19) in Sec. III. It is easy to show that $U_{C'_y C}$ is normalized as it should, so $\sum_{C'_y} U_{C'_y C} = 1$.

In order to measure current fluctuations we need to provide a microscopic definition of the energy current involved in an elementary move. There are many different ways to define this current: the energy exchanged per unit time with one of the boundary heat baths, the current flowing between two given nearest neighbors or its spatial average, etc. Assuming that energy cannot accumulate in the system *ad infinitum* [6,7,25], all these definitions give equivalent results for the current large deviation function in the long-time limit. However, this is not so for some observables different from the large deviation function (e.g., for average profiles measured *at the end* of the large deviation event; see Ref. [22]). In our case, the following choice turns out to be convenient

$$J_{C'_y C} = \begin{cases} \frac{e_y - e'_y}{N-1} & y \in [1, N-1] \text{ (bulk exchange)} \\ 0 & y = 0, N \text{ (boundary baths)} \end{cases}. \quad (\text{C9})$$

That is, we measure the energy current flowing through the bulk of the system. Using this current definition and Eq. (C8), we may write the modified normalized dynamics $U'_{C'_y C} \equiv Y_C^{-1} U_{C'_y C} \exp[\lambda J_{C'_y C}]$, which for $y \in [1, N-1]$ reads

$$U'_{C'_y C} = \frac{e^{\bar{\lambda}(e_y - e'_y)}}{Y_C(N+1)}, \quad (\text{C10})$$

with $\bar{\lambda} = \lambda / (N-1)$, while $U'_{C'_y C} \equiv Y_C^{-1} U_{C'_y C}$ for $y = 0, N$, see Eq. (C9). The exit rate is given by

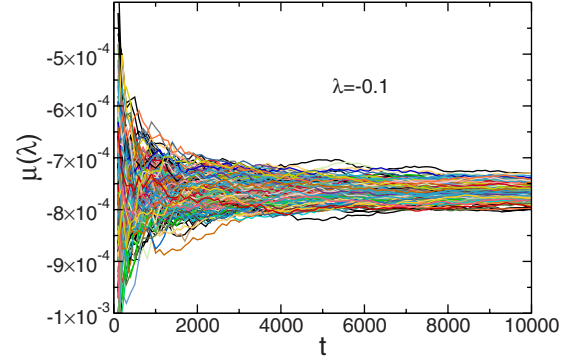


FIG. 17. (Color online) Time evolution of $\mu(\lambda)$ for $\lambda = -0.1$ and many different initial conditions. Here $N=50$, $M=10^3$, and $T_L=2$, $T_R=1$.

$$Y_C = \frac{2}{N+1} + \sum_{y=1}^{N-1} \frac{e^{\bar{\lambda}e_y} - e^{-\bar{\lambda}e_{y+1}}}{\bar{\lambda}(N+1)(e_y + e_{y+1})}. \quad (\text{C11})$$

In these paper, we simulate a system of size $N=50$, with $T_L=2$ and $T_R=1$, using $M=10^3$ copies of the system and a maximum time of $t=10^4$ Monte Carlo steps. For a given initial condition, we average the measured $\mu(\lambda)$ for different times once in the steady state, after a relaxation time of 2×10^3 Monte Carlo steps. In addition, we average results over many independent initial conditions, in which local initial energies e_i are randomly drawn according to the Gibbs distribution with temperature parameter $T_{\text{st}}[x=i/(N+1)]$ corresponding to the linear, steady temperature profile. Figure 17 shows the convergence of $\mu(\lambda)$ in time for a given value of λ and many different initial conditions. Using the above method, we obtained an accurate measurement of the current large deviation function, see Fig. 3 in Sec. IV.

APPENDIX D: TIME REVERSIBILITY AND STATISTICS DURING A LARGE FLUCTUATION

In this Appendix, we use the time reversibility of the underlying stochastic dynamics to study the system statistics during a large deviation event and the symmetries of the large deviation function and the associated optimal profiles, using the formalism described in Appendix C. In particular, we describe a relation between system statistics at the end of the large deviation event and for intermediate times. First, consider the probability $P(C_t, Q_t, t)$ that the system is in configuration C_t at time t with a total time-integrated current Q_t . As in the previous appendix, we drop the dependence of this probability on the initial state C_0 , which we assume lost for long enough times. This probability obeys the following master equation

$$P(C_t, Q_t, t) = \sum_{C'} U_{C_t C'} P(C', Q_t - J_{C_t C'}, t-1), \quad (\text{D1})$$

which by iterating in time leads to

$$P(C_t, Q_t, t) = \sum_{C_{t-1} \dots C_1} U_{C_t C_{t-1}} \dots U_{C_1 C_0} \delta \left(Q_t - \sum_{k=0}^{t-1} J_{C_{k+1} C_k} \right), \quad (\text{D2})$$

and it is clear that $P(Q_t, t) = \sum_{C_t} P(C_t, Q_t, t)$, see Eq. (C1) in the previous appendix. Now, $P_q^{\text{end}}(C_t) \equiv P(C_t, Q_t, t) / P(Q_t, t; C_0)$ is the probability of having a configuration C_t at the end of a large deviation event associated to a current $q = Q_t/t$. Defining $\Pi(C_t, \lambda, t) = \sum_{Q_t} \exp(\lambda Q_t) P(C_t, Q_t, t)$ so that

$$\Pi(C_t, \lambda, t) = \sum_{C_{t-1} \dots C_1} \tilde{U}_{C_t C_{t-1}} \dots \tilde{U}_{C_1 C_0}, \quad (\text{D3})$$

with $\tilde{U}_{C'C}(\lambda) = U_{C'C} \exp(\lambda J_{C'C})$, one can easily show that, for long times t , $P_\lambda^{\text{end}}(C_t) \equiv \Pi(C_t, \lambda, t) / \Pi(\lambda, t) = P_{q_o(\lambda)}^{\text{end}}(C_t)$, where $q_o(\lambda)$ is the current conjugated to parameter λ , and $\Pi(\lambda, t)$ is defined in Eq. (C3). Using the spectral decomposition of Appendix C, it is simple to show that $P_q^{\text{end}}(C_t) \propto \langle C_t | \Lambda^R(\lambda) \rangle$, so the right eigenvector $|\Lambda^R(\lambda)\rangle$ associated to the largest eigenvalue of matrix $\tilde{U}(\lambda)$ gives the probability of having any configuration at the end of the large deviation event. Noticing that, for the Monte Carlo algorithm described in the previous appendix, the fraction of clones or copies in state C_t is proportional to $\langle C_t | \Lambda^R(\lambda) \rangle$ for long times, see Eq. (C7), we deduce that the average profile among the set of clones yields the mean temperature profile at the end of the large deviation event, $T_\lambda^{\text{end}}(x)$.

The initial and final time regimes during a large deviation event show transient behavior which differs from the behavior in the *bulk* of the large deviation event, i.e., for intermediate times [6]. In particular, as we will show here, midtime and endtime statistics are different, though intimately related as a result of the time reversibility of the microscopic dynamics. Let $\bar{P}(C_\tau, \lambda, \tau, t)$ be the probability that the system was in configuration C_τ at time τ when at time t the total integrated current is Q_t . Timescales are such that $1 \ll \tau \ll t$, so all times involved are long enough for the memory of the initial state C_0 to be lost. We can write now

$$\begin{aligned} \bar{P}(C_\tau, Q_t, \tau, t) &= \sum_{C_\tau \dots C_{\tau+1} C_{\tau-1} \dots C_1} U_{C_\tau C_{\tau-1}} \dots U_{C_{\tau+1} C_\tau} \\ &\times U_{C_\tau C_{\tau-1}} \dots U_{C_1 C_0} \delta \left(Q_t - \sum_{k=0}^{t-1} J_{C_{k+1} C_k} \right), \end{aligned} \quad (\text{D4})$$

where we do not sum over C_τ . Defining the moment-generating function of the above distribution, $\bar{\Pi}(C_\tau, \lambda, \tau, t) = \sum_{Q_t} \exp(\lambda Q_t) \bar{P}(C_\tau, Q_t, \tau, t)$, we can again check that the probability weight of configuration C_τ at intermediate time τ in a large deviation event of current $q = Q_t/t$, $P_\lambda^{\text{mid}}(C_\tau) \equiv \bar{P}(C_\tau, Q_t, \tau, t) / P(Q_t, t)$, is also given by $P_\lambda^{\text{mid}}(C_\tau) \equiv \bar{\Pi}(C_\tau, \lambda, \tau, t) / \Pi(\lambda, t)$ for long times such that $1 \ll \tau \ll t$,

with $q = q_o(\lambda)$. In this long-time limit one thus finds

$$P_\lambda^{\text{mid}}(C_\tau) \propto \langle \Lambda^L(\lambda) | C_\tau \rangle \langle C_\tau | \Lambda^R(\lambda) \rangle, \quad (\text{D5})$$

in contrast to $P_\lambda^{\text{end}}(C)$, which is proportional to $\langle C | \Lambda^R(\lambda) \rangle$, see above. Here $|\Lambda^R(\lambda)\rangle$ and $\langle \Lambda^L(\lambda)|$ are the right and left eigenvectors associated to the largest eigenvalue $e^{\Lambda(\lambda)}$ of modified transition rate $\tilde{U}(\lambda)$, respectively. They are different because \tilde{U} is not symmetric. In order to compute the left eigenvector, notice that $|\Lambda^L(\lambda)\rangle$ is the *right* eigenvector of the transpose matrix $\tilde{U}^T(\lambda)$ with eigenvalue $e^{\Lambda(\lambda)}$. This right eigenvector of $\tilde{U}^T(\lambda)$ can be in turn related to the corresponding right eigenvector of $\tilde{U}(-\lambda - \mathcal{E})$ by noticing that the local detailed balance condition holds for the KMP model, guaranteeing the time reversibility of microscopic dynamics. This condition states that $U_{C'C} p_{\text{eq}}(C) = U_{CC'} p_{\text{eq}}(C') e^{\mathcal{E} J_{C'C}}$, where $p_{\text{eq}}(C)$ is an effective equilibrium weight which for the KMP model takes the value $p_{\text{eq}}(C) = \exp(-\sum_{y=1}^N \beta_y e_y)$ with $C = \{e_y, y = 1 \dots N\}$ and $\beta_y = T_L^{-1} + \mathcal{E} \frac{y-1}{N-1}$. Local detailed balance then implies a symmetry between the forward modified dynamics for a current fluctuation and the time-reversed modified dynamics for the negative current fluctuation, i.e., $\tilde{U}_{CC'} = p_{\text{eq}}^{-1}(C') \tilde{U}(-\lambda - \mathcal{E}) p_{\text{eq}}(C)$ or in matrix form

$$\tilde{U}^T(\lambda) = \mathbf{P}_{\text{eq}}^{-1} \tilde{U}(-\lambda - \mathcal{E}) \mathbf{P}_{\text{eq}}, \quad (\text{D6})$$

where \mathbf{P}_{eq} is a diagonal matrix with entries $p_{\text{eq}}(C)$. Equation (D6) implies that all eigenvalues of $\tilde{U}(\lambda)$ and $\tilde{U}(-\lambda - \mathcal{E})$ are equal, and in particular the largest, so $\mu(\lambda) = \mu(-\lambda - \mathcal{E})$ and this proves the Gallavotti-Cohen fluctuation relation. Moreover, if $|\Lambda_j^R(-\lambda - \mathcal{E})\rangle$ is a right eigenvector of $\tilde{U}(-\lambda - \mathcal{E})$, which can be expanded as $|\Lambda_j^R(-\lambda - \mathcal{E})\rangle = \sum_C \langle C | \Lambda_j^R(-\lambda - \mathcal{E}) \rangle |C\rangle$, then

$$|\Lambda_j^L(\lambda)\rangle = \sum_C (p_C^{\text{eq}})^{-1} \langle C | \Lambda_j^R(-\lambda - \mathcal{E}) \rangle |C\rangle, \quad (\text{D7})$$

is the right eigenvector of $\tilde{U}^T(\lambda)$ associated to the same eigenvalue. In this way, by plugging this into Eq. (D5) we find

$$P_\lambda^{\text{mid}}(C) \propto (p_C^{\text{eq}})^{-1} \langle C | \Lambda^R(-\lambda - \mathcal{E}) \rangle \langle C | \Lambda^R(\lambda) \rangle,$$

where we assumed real components for the eigenvectors associated to the largest eigenvalue. Equivalently

$$P_\lambda^{\text{mid}}(C) = A \frac{P_\lambda^{\text{end}}(C) P_{-\lambda - \mathcal{E}}^{\text{end}}(C)}{p_C^{\text{eq}}}, \quad (\text{D8})$$

with A a normalization constant. This relation implies that configurations with a significant contribution to the average profile at intermediate times are those with an important probabilistic weight at the end of both the large deviation event and its time-reversed process. Supplementing the above relation with a local equilibrium hypothesis, one can obtain average temperature profiles at intermediate times in terms of profile statistics at the end of the large deviation event.

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