Effects of Static and Dynamic Disorder on the Performance of Neural Automata

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Abstract

We report on both analytical and numerical results concerning stochastic Hopfield-like neural automata exhibiting the following (biologically inspired) features: (1) Neurons and synapses evolve in time as in contact with respective baths at different temperatures. (2) The connectivity between neurons may be tuned from full connection to high random dilution or to the case of networks with the small–world property and/or scale-free architecture. (3) There is synaptic kinetics simulating repeated scanning of the stored patterns. Though these features may apparently result in additional disorder, the model exhibits, for a wide range of parameter values, an extraordinary computational performance, and some of the qualitative behaviors observed in natural systems. In particular, we illustrate here very efficient and robust associative memory, and jumping between pattern attractors.

The model and its motivation

The field of neural automata, or cellular automata [1] that are biologically inspired and aimed at solving open issues in neuroscience, may be said to initiate with the Hopfield model [2]. This illustrates —on very simple and, consequently, rather unrealistic grounds— the property of associative memory, a task for which natural systems remain far from unbeaten by digital computers. Besides many other related studies [3], the Hopfield model has been generalized along three interesting lines. That is, it has been shown that one may enhance the computational abilities of a Hopfield–like system by allowing for dynamic —instead of quenched— synapses [4, 5], by implementing dynamics in the computer via parallel —instead of sequential— updating [6, 7], and by considering scale–free —instead of extremely connected— network topologies [8, 9]. In this paper we report on some recent efforts along these lines. We describe a stochastic neural automata scheme that allows for explicitly studying the influence of the model
The function $\Psi(\beta)$ typically involves both an inverse temperature $\beta$ and the corresponding change $\Delta H$ of the chosen energy function. In the standard Hopfield model, for instance, one assumes $M$ patterns consisting of binary variables, $\xi_{ij}^\mu = \pm 1$, $\mu = 1, \ldots, M$, and the weights are then set according to some learning rule. A familiar instance is the Hebb's rule for which the synapses take values $w_{ij} \propto \sum_{\mu} \xi_{ij}^\mu \xi_{ij}$.

The system configuration at time $t$ involves the sets $S \equiv \{s_i\}$ and $W \equiv \{w_{ij}\}$ which together determine the value of some energy function. To be specific, consider this to be $H(S, W; t) = -\frac{1}{2} \sum_i \sum_{ij} w_{ij}(t) s_i s_j$ where the second sum goes over all nodes connecting to $i$. That is, we are assuming that there is an energy function with the Ising structure at each time $t$, and that synapses vary with $t$. For simplicity, we further assume that $w_{ij}(t) = \tilde{w}_{ij}(\mu(t)) = \sigma N^{-1} \xi_{ij}^\mu(t)$, where $\sigma$ is a normalization constant. This amounts to set each connection at time $t$ equal to the value obtained from the $\mu$ th pattern via a learning rule. And our choice for this (see what follows) is such that, after time averaging, it results in the Hebb’s rule (i.e. we average over all patterns with the same height). A main fact is that, consistently with the empirical observation that memory is a global dynamic phenomenon, we are assuming that all local synapses are set at each time by a given pattern, which is chosen according to some dynamics to be determined next.

One is mainly interested in $m \equiv \{m^\mu; \mu = 1, \ldots, M\}$, where $m^\mu = \langle m^\mu(S) \rangle$ is the overlap between the current state $S$ and pattern $\mu$. We assume $[13][15]$ that $(S, \mu)$ evolves in discrete time according to a transition rate $T$ that may be decomposed as: $T_{\mu'}[S' \to S] \times T_{S}[\mu' \to \mu]$. Here, $T_{\mu}$ is taken as a product of $N$ terms $\Psi[\beta_0 \Delta H(s_i' \to s_i = \pm s')]$ (as corresponds to the neuron configuration varying by parallel updating or Little dynamics), and $T_{S} = \Psi[\beta_1 \Delta H(\mu' \to \mu)]$. The function $\Psi(X)$ is arbitrary, e.g., of the Glauber type $[10]$, and each transition rate involves both an inverse temperature $\beta$ of the bath inducing its own stochasticity and the corresponding change $\Delta H$ of the chosen energy function.

The fact that the neuron activities and the synaptic intensities are stochastically driven by different parameters, $\beta_0^{-1}$ and $\beta_1^{-1}$, respectively—which one may imagine the temperatures of two different baths in contact with each
set of degrees of freedom—endows the neural automata with a varied and interesting behavior. This is related to the fact that the competition between baths impedes the system from reaching thermal equilibrium; in general, the asymptotic state is instead a nonequilibrium steady state, which is more realistic than an equilibrium one [16]. Though the baths competition is, to the best of our knowledge, a novel feature within the present context, our model has some close antecedents [17, 18, 19]; these, however, mainly concern sequential updating, which in general results in a less efficient mechanism [15]. Furthermore, our model describes the changes in the two subsystems on the same time scale, which is an interesting general situation with well-defined limits. That is, \( \beta_1 \to \infty \) corresponds to the freezing of synapses [2], large \( \beta_1 \) is for slow synaptic kinetics [17], and small \( \beta_1 \) describes extreme synaptic activity [5, 18].

This neural automata is also simple and versatile enough to allow for analyzing different network architectures. With this aim, we (i) first generated a network starting with \( \eta_0 \) nodes and adding \( \eta \leq \eta_0 \) links at consecutive time steps with the preferential attachment rule. This, resulting in \( \eta(N - \eta_0) \) links for \( N \) nodes, will be called the scale–free (Barabasi-Albert) network (SFN) [12]. (ii) A fully connected network (FCN) with \( N \) nodes has \( N^2 \) links, which is not realistic for a neural system. Instead, (iii) a meaningful alternative to the SFN case is the (highly) diluted network (DN) obtained by randomly suppressing links in the FCN until only \( \eta(N - \eta_0) \) are left. In order to have a true SFN with the small–world property, i.e., most of the nodes exhibiting small connectivity and a few hubs having its connectivity comparable to the network size \( N \), one needs to restrict to \( \eta <\ll N \).

**Scale–free topology of synapses**

The small–world property, which implies that the average path length between any two nodes is very small compared to the network typical length, is a suitable feature for an efficient neural system. In fact, this property has been reported to hold in many natural systems [12, 20], including growing cultured neurons [10], and it was shown that the SFN can store and retrieve a given number of patterns with a lower computer–memory cost that the FCN [8]. We shall briefly illustrate here (see also Ref. [9]) that the scale–free architecture may indeed enhance both the network associative performance and its robustness against thermal noise perturbations.

The graphs in fig.1 show the dependence of the stationary overlap \( m^\mu \) on the neuron temperature, \( T \equiv \beta_0^{-1} \), for cases SFN and DN with \( \eta = 3 \) and \( M = 1 \). Notice that the SFN with competing temperatures coincides for \( M = 1 \) with the standard, equilibrium Hopfield model (with quenched synapses). Fig.1 illustrates that the SFN makes indeed a better job for retrieving of information than the comparable DN at sufficiently high temperature, which is the relevant case for practical purposes. As \( M \) is increased, the performance tends to deteriorate in both cases. However, one then observes an intriguing behavior of the SFN at finite temperature. That is, there is a definite tendency of the
hubs, namely, nodes with \( k \geq k_0 (M, \beta_0, \beta_1) \), to concentrate most of the system activity concerning the retrieval process.

In order to illustrate the above property, we computed the mean local overlap associated to a node of degree \( k \), \( m(k) \). The resulting graphs in fig.2 clearly depict that \( m(k) \to 1 \) as \( k \) increases at any temperature (large fluctuations simply reflect that the number of hubs is small for the network size used). This indicates how the hubs, the more the higher its connectivity degree, tend to become robust references for the process of associative memory. The state of boundary nodes, on the contrary, shows a poor correlation with the relevant stored pattern. This is in agreement with a previous observation at zero (neuron) temperature [21]. The above results triggered our interest in networks in which the connectivity degree is power–law distributed, \( P(k) \sim k^{-\gamma} \). An issue is the possible influence of the parameter \( \gamma \) on the system performance. In fact, the number of highly connected nodes tends to sharply decrease as \( \gamma \) is increased, and it ensues \( \gamma \lesssim 2 \) as a convenient range. Further study of this will be reported elsewhere [9].

**Escaping from the attractor**

Time behavior is also intriguing as illustrated, for instance, by the FCN architecture, which is more amenable to analysis. Fig.3 depicts the various phases exhibited by the system as the parameters \( \beta_0 \) and \( \beta_1 \) are changed. There is a ferromagnetic (F) phase in which the system shows associative memory, and a paramagnetic (P) phase —the upper stripe— lacking this property. This is familiar from the Hopfield model. A first novelty is that no mixed states [15] oc-
cur, which is computationally convenient. In addition, the nonequilibrium phase diagram in fig.3 depicts a region between the P and F phases that exhibits emergent dynamic behavior confirming (and extending) a result in Ref. [11]. That is, the system in this region has dynamic associative memory, namely, after a transient time in which one of the stored patterns is recovered, the system jumps to one of the other possible attractors, and keeps indefinitely doing so. The

![Figure 2: The local overlap, as defined in the main text, versus the connectivity degree k for different T, increasing from top to bottom, for the scale–free network in fig. 1. This illustrates a tendency of the hubs to control the retrieval of information.](image)

nature of this jumping deserves a comment. Simulations uncover that there is some non–trivial structure of time correlations. This is revealed by monitoring the time $\tau_{\nu,\zeta}$ the system stays in attractor $\nu$ before escaping to another one, say $\zeta$. Within the largest jumping region, O(II), $\tau_{\nu,\zeta}$ happens to be practically independent of both $\nu$ and $\zeta$. That is, the system then stays the same amount of time wandering in each attractor. However, the probability of jumping between patterns depends on the activities, and non–trivial time correlations develop as the neuron temperature is lowered, namely, in region O(I), where one even observes that $\tau_{\nu,\zeta} \neq \tau_{\zeta,\nu}$. The behavior in O(I) suggests using our algorithm to code spatial–temporal information [22].

Summing up, we have illustrated several aspects of the behavior of Hopfield–like neural automata. This consists of neurons and synapses that evolve on the same time scale but subject to different thermal noises. Furthermore, different network architectures have been considered. It follows that a power–law topology, which is known to characterize many natural, including neural systems is advantageous compared to the corresponding diluted network. We also find definite evidence that hubs, i.e. the few most highly connected nodes in a scale–free architecture, play a fundamental role in making the retrieval of information more robust and efficient. These findings, whose validity in natural systems is to be checked, suggest paths for a convenient design of artificial systems. We have also demonstrated that, for appropriate parameter values,
neural automata perform much more efficiently when one lets the subsystem of synapses to constantly and coherently visit all the stored patterns in a convenient way. This is fully consistent with two main empirical observations, namely, that memory is a global dynamic phenomenon, and that oscillations are essential to cortex functions. The neural automata has also been shown to exhibit in some situations spatial–temporal attractors, which may be relevant to simple olfactory processing, for instance. We acknowledge financial support

Figure 3: Phase diagram for the FCN automata depicting three coexistence curves that define several phases; see the main text.

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References


It is worth remarking that this and several other details here are rather arbitrary. They mainly intend an easy illustration of the relevant result, and can generally be waived or modified — some times rather straightforwardly.


